## SPAJ 140 C

## Overcurrent and earth-fault relay

## User's manual and Technical description


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The complete manual for the relay SPAJ 140 C contains the following submanuals:

General relay description for SPAJ 140 C
1MRS 750629-MUM EN
1MRS 750066-MUM EN
1MRS 750119-MUM EN

## Features

Three-phase, low-set phase overcurrent unit with definite time or inverse definite minimum time (IDMT) characteristic

Three-phase, high-set phase overcurrent unit with instantaneous or definite time function

Low-set, non-directional earth-fault unit with definite time or inverse definite minimum time (IDMT) characteristic

High-set, non-directional earth-fault unit with instantaneous or definite time function

Built-in breaker failure protection function
Two heavy-duty and four light-duty output relays with field-selectable configuration

Extensive data communication capabilities over built-in serial port

Outstanding design flexibility for easy selection of appropriate operation schemes for different applications

Numerical display of setting values, measured values, memorized fault values, fault codes etc.

Enhanced system reliability and availability due to continuous hardware and software self-supervision with auto-diagnosis

Powerful software support for setting and parametrizing of the relay and for recording of relay parameters with a portable PC.

## Application

The combined overcurrent and earth-fault relay SPAJ 140 C is intended to be used for the selective short-circuit and earth-fault protection of radial feeders in solidly earthed, resistance earthed or impedance earthed power systems. The integrated protection relay includes a phase overcurrent unit and an earth-fault unit with
flexible tripping and signalling facilities. The overcurrent and earth-fault relays can also be used inother applications requiring single-, twoor three-phase overcurrent protection and nondirectional earth-fault protection. The combined overcurrent and earth-fault relay also features circuit breaker failure protection.

The combined overcurrent and earth-fault relay is a secondary relay to be connected to the current transformers of the protected object. The three-phase overcurrent unit and the earthfault unit continuously measure the phase currents and the neutral current of the protected object. On detection of a fault the relay starts, trips the circuit breaker, initiates auto-reclosing, provides alarm, records fault data etc. in accordance with the application and the configured relay functions.

When the phase current exceeds the set start current of the low-set stage I>, the overcurrent unit starts delivering a start signal after a preset -60 ms start time. When the set operate time at definite time operation or the calculated operate time at inverse time operation elapses, the overcurrent unit operates. In the same way the highset stage I $\gg$ of the overcurrent unit starts delivering a start signal after a preset -40 ms start time, when the set start current is exceeded. When the set operate time elapses, the overcurrent unit operates.

When the earth-fault current exceeds the set start current of the low-set stage $\mathrm{I}_{0}>$, the earthfault unit starts delivering a start signal after a preset -60 ms start time. When the set operate time at definite time operation or the calculated operate time at inverse time operation elapses, the earth-fault unit operates. In the same way the high-set stage $\mathrm{I}_{0} \gg$ of the earth-fault unit
starts delivering a start signal after a preset $\sim 40$ ms start time, when the set start current is exceeded. When the set operate time elapses, the earth-fault unit operates.

The low-set stage of the overcurrent unit and the low-set stage of the earth-fault unit may be given definite time or inverse definite minimum time (IDMT) characteristic. When the IDMT characteristic is chosen six time/current curves are available. Four of the curves comply with the BS 142 and IEC 60255 and are named "Normal inverse", "Very inverse", "Extremely inverse" and "Long-time inverse". The two additional inverse time curves called the "RI-curve" and the "RXIDG-curve" are also provided.

By appropriate configuration of the output relay matrix, the start signals of the overcurrent and earth-fault units are obtained as contact functions. The start signals can be used for blocking co-operating protection relays, for signalling and for initiating auto-reclosing.

The relay includes one external binary input, which is controlled by an external control voltage. The function of the control input is determined by selector switches in the protection relay module. The control input can be used for blocking the operation of one or more protection stages, for resetting a latched output relay in the manual reset mode or for enforcing a new set of relay setting parameters by remote control.


Fig. 1. Protection functions of the combined overcurrent and earth-fault relay type SPAJ 140 C.

## Connections

(modified 2003-09)


Fig. 2. Connection diagram for the combined overcurrent and earth-fault relay type SPAJ 140 C.
$\mathrm{U}_{\text {aux }} \quad$ Auxiliary voltage
A, B, C, D, E, F
IRF
SGR
SGB
TRIP
SIGNAL 1
SIGNAL 2
START 1
START 2
U1
U3
U2
Output relays
Self-supervision
Switchgroups for the configuration of the output relays
Switchgroup for the configuration of the blocking or control signal
Trip output relay
Signal on operation of the overcurrent unit
Signal on operation of the earth-fault unit
Starting or auxiliary trip signal as selected with switchgroup SGR3
Start signal of the low-set overcurrent stage I>
Overcurrent and earth-fault relay module SPCJ 4D29
Input module SPTE 4E1
Power supply and output relay module SPTU 240 R1 or SPTU 48 R1
Start and operation indications
Serial communication port
Bus connection module
Receiver bus terminal ( Rx ) and transmitter bus terminal ( Tx ) of the bus connection module


Fig. 3. Terminal arrangement of the overcurrent and earth-fault relay type SPAJ 140 C.

The energizing currents of the overcurrent unit are connected to terminals $1-2,4-5$ and $7-8$, when the rated current of the CT secondary circuits is $I_{n}=5 \mathrm{~A}$. When the rated current of the CT secondary circuits is $I_{n}=1 \mathrm{~A}$, terminals 1-3, $4-6$ and 7-9 are used. The relay can also be used in single-phase or two-phase applications simply by leaving one or two energizing inputs unoccupied. In single-phase applications the same energizing current can be routed through two energizing inputs, which may increase the operating speed of the overcurrent unit, especially at instantaneous operation.

The energizing current for the earth-fault unit is connected to terminals $25-26$ when the rated current $I_{n}=5 \mathrm{~A}$ and to terminals 25-27 when the rated current $I_{n}=1 \mathrm{~A}$.

The control input 10-11 can be used in three different ways, i) as control input for an external blocking signal, ii) as the control input for unlatching the trip relay, or iii) as the control input for the remote control of relay settings. The requested function is selected by means of switches switchgroup SGB in the main menu of the protection relay module.

The auxiliary supply voltage of the relay is connected to terminals 61-62. At d.c. supply the positive lead is connected to terminal 61. The level of the voltage to be applied to the terminals depends on the type of power supply and output relay module inserted in the relay. For further details see the description of the power supply module. The permitted auxiliary voltage range of the relay is marked on the relay front panel.

Output relay A is a heavy-duty trip relay capable of controlling most circuit breakers. The operate signals of the different protection stages are routed to the trip relay with switches $2,4,6$ and 8 of switchgroup SGR1. On delivery from the factory all the protection stages are routed to the trip relay. A latching of the output relay A can be selected with switches 6 and 7 of switchgroup SGB.

Output relays B and C can be used for signalling on operation of the relay module. The signals to be routed to the output relays $B$ and $C$ are
selected with switches $1 . . .8$ of switchgroup SGR2. The switch matrixes for routing operate signals to the output relays B and C are identical. Normally output relay B is used for signalling on operation of the overcurrent unit and C for signalling on operation of the earth-fault unit. This is also the default setting of the relay on delivery from the factory.

The start signals of the protection stages of the relay are routed to output relay $D$. The signals to be routed to output relay D are selected by means of switches $1,3,5$ and 7 of switchgroup SGR1, which is a software switchgroup found in the main menu of the protection relay module. The start signals of the low-set and high-set stage of the overcurrent unit are selected with switches 1 and 3, and the start signals of the high-set and low-set stage of the earth-fault unit with switches 5 and 7.

The output relay E is a heavy-duty relay as output relay A. It can be controlled by the start and operate signals of the protection stages. Output relay E is also used a trip relay for the circuit breaker failure protection (CBFP), when the CBFP protection is used. In this case the trip signal can be used either to control a circuit breaker upstreams or to control a second trip coil on the main circuit breaker to increase the redundancy of the circuit breaker.

Output relay F functions as output relay for the self-supervision system of the protection relay. The F relay is energized under normal operating conditions and contact gap 70-72 is closed. If a fault is detected by the self-supervision system, or on loss of auxiliary supply, the output relay drops off and the NO contact 71-72 closes.

By means of bus connection modules type SPA -ZC17 and SPA-ZC21 the relay connects to the fibre-optic SPA bus via a 9-pole, D-type subminiature connector located at the rear panel of the relay. The terminals of the fibre-optic cables are connected to the counter terminals Rx (receiver) and $\mathrm{Tx}^{\text {(transmitter) of the bus con- }}$ nection module. The fibre-optic cables are linked from one relay to another and to the substation level communication unit, for instance type SRIO 1000M.

The figure below schematically illustrates how the start, trip, control and blocking signals can
be configured to obtain the required protection functions.


Fig. 4. Signal diagram of the combined overcurrent and earth-fault relay type SPAJ 140 C

The functions of the blocking and start signals are selected with the switches of switchgroups SGF, SGB and SGR. The checksums of the switchgroups, are found in the setting menu of
the protection relay module. The functions of the different switches are explained in detail in the user's manual of the protection relay module SPCJ 4D29.

## Signal abbreviations

| $\mathrm{I}_{\text {L1 }}, \mathrm{I}_{\text {L2 }}, \mathrm{I}_{\text {L3 }}$ | Energizing current of phase L1, L2 and L3 <br> $\mathrm{I}_{0}$ <br> Neutral current (Residual current) |
| :--- | :--- |
| BS | Blocking or control signal |
| SS1 | Start signal 1 |
| SS2 | Start signal 2 |
| SS3 | Start signal 3 |
| TS1 | Operate signal 1 (Trip signal 1) |
| TS2 | Operate signal 2 (Trip signal 2) |
| BS | Blocking signal |
| AR1...3 | Atuto-reclose start signals (not in use in relay SPAJ 140 C) |
| IRF | Internal relay failure |
| SGF | Switchgroup for functions |
| SGB | Switchgroup for blockings |
| SGR | Switchgroup for relay configuration |

A) The indicator TRIP is lit when one of the protection stages operates. When the protection stage resets, the red indicator remains lit.
B) If the display is dark when one of the protection stages $\mathrm{I}>, \mathrm{I} \gg, \mathrm{I}_{0}>$ or $\mathrm{I}_{0} \gg$ operates, the faulty phase or the neutral circuit is indicated with a yellow LED. If, for instance, the TRIP indicator glows red, and the indicators $\mathrm{I}_{\mathrm{L} 1}$ and $\mathrm{I}_{\mathrm{L} 2}$ at the same time are lit, overcurrent has occurred on phase L1 and L2.
C) Besides being a code number at data presentation, the leftmost red digit in the display serves as a visual operation indicator. An operation indicator is recognized by the fact that the red digit alone is switched on. The following table named OPERATION IND. on the relay front panel is a key to the function code numbers used.

| Indication | Explanation |  |
| :---: | :--- | :--- |
| 1 | I $>$ START | $=$ The low-set stage I $>$ of the overcurrent unit has started |
| 2 | I $>$ TRIP | $=$ The low-set stage I $>$ of the overcurrent unit has operated |
| 3 | I $\gg$ START | $=$ The high-set stage I $\gg$ of the overcurrent unit has started |
| 4 | I $\gg$ TRIP | $=$ The high-set stage I $\gg$ of the overcurrent unit has operated |
| 5 | $\mathrm{I}_{0}>$ START | $=$ The low-set stage $\mathrm{I}_{0}>$ of the earth-fault unit has started |
| 6 | $\mathrm{I}_{0}>$ TRIP | $=$ The low-set stage $\mathrm{I}_{0}>$ of the earth-fault unit has operated |
| 7 | $\mathrm{I}_{0} \gg$ START | $=$ The high-set stage $\mathrm{I}_{0} \gg$ of the earth-fault unit has started |
| 8 | $\mathrm{I}_{0} \gg$ TRIP | $=$ The high-set stage $\mathrm{I}_{0} \gg$ of the earth-fault unit has operated |
| 9 | CBFP | $=$ Circuit breaker failure protection has operated |

D) The TRIP indications persist when the protection stage returns to normal. The indicator is reset by pushing the RESET/STEP push-button.

Further, the indicators may be reset via the external control input $10-11$ by applying a control voltage to the input, provided switch SGB/8 is in position 1.

The basic protection relay functions are not depending on the state of the operation indicators, reset or non-reset. The relay is permanently operative.

If a protection stage starts, but not operates, because the energizing quantity goes below the set start current before the operate time circuit has timed out, the start indicators are normally automatically switched off. However, by means of the switches SGF2/1... 4 the start indications may be made persistant which means that they are to be manually reset by pushing the RESET/ STEP push-button. The persistent indications are obtained through the following switch settings.

SGF2/1 = 1 manual reset of $\mathrm{I}>$ start indication SGF2/2 $=1$ manual reset of $\mathrm{I} \gg$ start indication SGF2/3 $=1$ manual reset of $\mathrm{I}_{0}>$ start indication SGF2/4 = 1 manual reset of $\mathrm{I}_{0} \gg$ start indication

On delivery of the relay from the factory the switches SGF2/1 $\ldots 4$ are preset at 0 .
E) Shortly after the internal self-supervision system has detected a permanent relay fault the red IRF indicator is switched on and the output relay of the self-supervision system operates. Further, in most fault situations an autodiagnostic fault code is shown in the display. The fault code is composed of a red figure 1 and a green code number which indicates fault type. The fault code persists until the STEP/RESET push-button is pressed. When a fault code appears on the display, the code number should be recorded for statistical and maintenance purposes.

Power supply and output relay module

To be able to operate the relay needs a secured auxiliary voltage supply. The power supply module forms the voltages required by the protection relay module and the auxiliary relays. The withdrawable power supply and output relay module is located behind the system front panel, which is fixed by means of four crossslotted screws. The power supply and output relay module contains the power supply unit, all output relays, the control circuits of the output relays and the electronic circuitry of the external control inputs.

The power supply and output relay module can be withdrawn after removing the system front
panel. The primary side of the power supply module is protected with a fuse, F 1 , located on the PCB of the module. The fuse size is 1 A (slow).

The power supply unit is a pulse-width modulated (PWM) dc/dc converter with galvanically isolated primary and secondary sides. It forms the dc secondary voltages required by the protection relay module; that is $+24 \mathrm{~V}, \pm 12 \mathrm{~V}$ and +8 V . The output voltages $\pm 12 \mathrm{~V}$ and +24 V are stabilized in the power supply module, while the +5 V logic voltage required by the protection relay module is stabilized in the protection relay module.


Fig. 5.Voltage levels of the power supply unit

A green LED indicator $\mathrm{U}_{\text {aux }}$ on the system front panel is lit when the power supply module is in operation. The supervision of the voltages supplying the electronics is located in the protection relay module. If a secondary voltage differs too much from its rated value, a self-supervision alarm will be generated. An alarm is also issued when the power supply module is withdrawn from the relay case, or on loss of auxiliary supply.

There are two versions of power supply and output relay modules available. For both types, the secondary sides and the relay configurations are identical, but the input voltage ranges differ.

Insulation test voltage between the primary and secondary side and the protective earth

$$
2 \mathrm{kV}, 50 \mathrm{~Hz}, 1 \mathrm{~min}
$$

Rated power $\mathrm{P}_{\mathrm{n}} \quad 5 \mathrm{~W}$
Voltage ranges of the power supply modules:

- SPTU 240 R1 U ${ }_{\text {aux }}=80 \ldots . .265 \mathrm{~V}$ dc/ac
- SPTU 48 R1 $U_{\text {aux }}=18 \ldots 80 \mathrm{~V}$ dc

The SPTU 240 R1 module can be fed from either an ac source or a dc source. SPTU 48 R1 is designed for dc supply only. The permitted auxiliary voltage range of the relay is marked on the relay system front panel.

## Technical data <br> Energizing inputs

(modified 2002-04)

| Rated current $\mathrm{I}_{\mathrm{n}}$ |  |  |
| :--- | :--- | :--- |
| Thermal withstand capability | 1 A | 5 A |
| - continuously | 4 A | 20 A |
| - for 1 s | 100 A | 500 A |
| Dynamic current withstand, half-wave value | 250 A | 1250 A |
| Input impedance | $<100 \mathrm{~m} \Omega$ | $<20 \mathrm{~m} \Omega$ |
| Rated frequency $\mathrm{f}_{\mathrm{n}}$, on request |  | 50 Hz or 60 Hz |

## Output contact ratings

Tripping contacts
Terminals
Rated voltage
Continuous carry
Make and carry for 0.5 s
Make and carry for 3.0 s
65-66, 74-75
$250 \mathrm{~V} \mathrm{dc} / \mathrm{ac}$
5 A

Breaking capacity for dc , when the trip circuit time-constant $\mathrm{L} / \mathrm{R} \leq 40 \mathrm{~ms}$, at $48 / 110 / 220 \mathrm{~V}$ dc

30 A
15 A

5 A/3 A/1 A

Signalling contacts
Terminals
Rated voltage
Continuous carry
Make and carry for 0.5 s
Make and carry for 3.0 s
70-71-72, 68-69, 77-78, 80-81
250 V dc/ac
5 A
10 A

Breaking capacity for dc, when the signal circuit time-constant $\mathrm{L} / \mathrm{R} \leq 40 \mathrm{~ms}$, at $48 / 110 / 220 \mathrm{~V}$ dc signal circuit voltage

8 A

1 A/0.25 A/0.15 A

## External control inputs

Blocking, remote reset or remote setting input
Control voltage level
Control current of activated input

## Power supply and output relay module

Supply and output relay module, type SPTU 240 R1
Supply and output relay module, type SPTU 48 R1
Power consumption under quiescent/operating conditions

10-11
$18 \ldots 265 \mathrm{~V}$ dc or $80 \ldots . .265 \mathrm{~V}$ ac $2 \ldots .20 \mathrm{~mA}$
$80 . . .265 \mathrm{~V} \mathrm{dc} / \mathrm{ac}$
$18 . . .80 \mathrm{~V} \mathrm{dc}$
$-4 \mathrm{~W} /-6 \mathrm{~W}$

Overcurrent unit of SPCJ 4D29
Low-set overcurrent stage I> *
Start current **

- at definite time characteristic
$0.5 \ldots 5.0 \times \mathrm{I}_{\mathrm{n}}$
- at inverse time characteristic ${ }^{* * *}$
$0.5 \ldots 2.5 \mathrm{x} \mathrm{I}_{\mathrm{n}}$
Time/current characteristic
- definite time characteristic - operate time $t>$
$0.05 \ldots 300$ s
- inverse definite minimum time (IDMT) characteristic as per IEC 60255-3 and BS 142
- special type inverse characteristic
- time multiplier k

High-set overcurrent stage I>>*
Start current
Operate time t>>

## Earth-fault unit of SPCJ 4D29

Low-set earth-fault stage $\mathrm{I}_{0}>$ *
Start current
Time/current characteristic

- definite time characteristic - operate time $t_{0}>$
- inverse definite minimum time (IDMT) characteristic as per IEC 60255-3 and BS 142
- special type inverse characteristic
- time multiplier $\mathrm{k}_{0}$

High-set earth-fault stage $\mathrm{I}_{0} \gg^{*}$
Start current
Operate time $\mathrm{t}_{0} \gg$

## * Note!

The operation of the low-set stage based on inverse time characteristic will be blocked by starting of the high-set stage. Then the operate time of the overcurrent unit is determined by the set operate time of the high-set stage at heavy fault currents. In order to obtain a trip signal, the high-set stage must be routed to a trip output relay.
** Note!
If the set start current exceeds $2.5 \times \mathrm{I}_{\mathrm{n}}$, the maximum continuous carry of the energizing inputs ( $4 \times \mathrm{I}_{\mathrm{n}}$ ) must be noted.

## *** CAUTION!

Never use start current settings above $2.5 \times \mathrm{I}_{\mathrm{n}}$ at inverse time operation although allowed by the relay.

## Data transmission

## Transmission mode

Fibre optic serial bus

Data code
ASCII
Selectable data transfer rates 4800 or 9600 Bd
Fibre optic bus connection modules for
powering from external power source

- for plastic core cables
- for glass fibre cables

Fibre optic bus connection modules for powering from host relay

- for plastic core cables
- for glass fibre cables


## Insulation Tests *)

Dielectric test IEC 60255-5
Impulse voltage test IEC 60255-5
Insulation resistance measurement IEC 60255-5

## Electromagnetic Compatibility Tests *)

High-frequency ( 1 MHz ) burst disturbance test
IEC 60255-22-1

- common mode
2.5 kV
- differential mode 1.0 kV

Electrostatic discharge test IEC 60255-22-2 and
IEC 61000-4-2

- contact discharge 6 kV
- air discharge 8 kV

Fast transient disturbance test IEC 60255-22-4
and IEC 61000-4-4

- power supply 4 kV
- I/O ports 2 kV

Spike test, class III (KEMA)
Magnetic field test acc. to IEC 60521
$1 \mathrm{kV}, 0.15 / 50 \mu \mathrm{~s}$
400 A/m

Power supply tests
Power supply variation
Variation voltage
68... 265 V

Interruption 80 V - 50\%
Interruption 80 V - 100\%
Interruption 255 V - 100\%
$0 . . .200 \mathrm{~ms}$
$0 . . .30 \mathrm{~ms}$
$0 . . .160 \mathrm{~ms}$

## Mechanical tests

Vibration tests
Shock and Bump tests
Seismic tests
IEC 60255-21-1, class 2
IEC 60255-21-2, class 2
ANS/IEEE C37.98-1987
-3.0 g in the horizontal direction

- 3.0 g in the vertical direction


## Environmental conditions

Corrosion test
Specified ambient service temperature range
Battelle-test

Long term damp heat withstand according to IEC 60068-2-3
Transport and storage temperature range
Protection by enclosure according to IEC 60529, when the relay is panel mounted
$-10 . . .+55^{\circ} \mathrm{C}$
$<95 \%$ at $40^{\circ} \mathrm{C}$ for 56 d
$-40 \ldots+70^{\circ} \mathrm{C}$

Mass of the relay including flush mounting relay case

IP 54
$-3.5 \mathrm{~kg}$
$\left.{ }^{*}\right)$ The tests do not apply to the serial port, which is used exclusively for the bus connection module.

Maintenance and repair

When the protection relay is operating under the conditions specified in the section "Technical data", the relay is practically maintenancefree. The relay modules include no parts or components subject to an abnormal physical or electrical wear under normal operating conditions.

If the environmental conditions at the relay operating site differ from those specified, as to temperature, humidity, or if the atmosphere around the relay contains chemically active gases or dust, the relay ought to be visually inspected in association with the relay secondary test or whenever the relay modules are withdrawn from the case. At the visual inspection the following things should be noted:

- Signs of mechanical damage on relay modules, contacts and relay case
- Accumulation of dust inside the relay cover or case; remove by blowing air carefully
- Rust spots or signs of erugo on terminals, case or inside the relay

On request, the relay can be given a special treatment for the protection of the printed circuit boards against stress on materials, caused by abnormal environmental conditions.

If the relay fails in operation or if the operating values remarkably differ from those of the relay specifications, the relay should be given a proper overhaul. Minor measures can be taken by personnel from the instrument work-shop of the customer's company, e.g. replacement of auxiliary relay modules. All major measures involving overhaul of the electronics are to be taken by the manufacturer. Please contact the manufacturer or his nearest representative for further information about checking, overhaul and recalibration of the relay.

Note!
Numerical protection relays contain electronic circuits which are liable to serious damage due to electrostatic discharge. Before removing a module containing electronic circuits, ensure that you are at the same electrostatic potential as the equipment, for instance, by touching the relay case.

## Note!

Static protection relays are measuring instruments and should be handled with care and protected against moisture and mechanical stress, especially during transport.

## Spare parts

Three-phase overcurrent and earth-fault module
Power supply and output relay module
$\mathrm{U}_{\text {aux }}=80 \ldots 265 \mathrm{~V} \mathrm{ac} / \mathrm{dc}$
$\mathrm{U}_{\text {aux }}=18 \ldots 80 \mathrm{~V}$ dc
Input module
Bus connection module

SPCJ 4D29
SPTU 240 R1
SPTU 48 R1
SPTE 4E1
SPA-ZC 17__ or SPA-ZC $21 \ldots$

The relay is housed in a normally flush-mounted case. The relay can also be arranged for semiflush mounting with the use of a $40 \mathrm{~mm}, 80 \mathrm{~mm}$ or 120 mm raising frame, which reduces the depth behind the panel by the same dimension. The type designations of the raising frames are SPA-ZX 111 for the 40 mm frame, SPA-ZX 112 for the 80 mm frame and SPA-ZX 113 for the 120 mm frame. A surface mounting case SPAZX 110 is also available.

The relay case is made of profile aluminium and finished in beige.

A cast aluminium alloy mounting frame with a rubber gasket provides a degree of protection by enclosure to IP 54 between the relay case and the
panel surface when the relay is panel mounted. The relay case is complete with a hinged gasketed, clear, UV-stabilized polycarbonate cover with a sealable fastening screw. The degree of protection by enclosure of the cover is also IP 54.

A terminal strip and two multipole connectors are mounted on the back of the relay case to facilitate all input and output connections. To each heavy duty terminal, i.e. measuring input, power supply or trip output, one $6 \mathrm{~mm}^{2}$, one $4 \mathrm{~mm}^{2}$ or one or two $2.5 \mathrm{~mm}^{2}$ wires can be connected. No terminal lugs are needed. The signalling outputs are available on a six pole detachable connector and the serial bus connection is using a 9-pin D-type connnector.


## Order information

1. Quantity and type designation
2. Rated frequency
3. Auxiliary voltage
4. Accessories
5. Special requirements

## Example

15 pcs relay type SPAJ 140 C
$\mathrm{f}_{\mathrm{n}}=50 \mathrm{~Hz}$
$\mathrm{U}_{\text {aux }}=110 \mathrm{~V}$ dc
15 pcs bus connection modules SPA-ZC17 MM
2 pcs fibre optical cables SPA-ZF MM 100 14 pcs fibre optical cables SPA-ZF MM 5

## General characteristics of D-type relay modules

## User's manual and Technical description


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The front panel of the relay module contains two push buttons. The RESET / STEP push button is used for resetting operation indicators and for stepping forward or backward in the display main menu or submenus. The PROGRAM push button is used for moving from a
certain position in the main menu to the corresponding submenu, for entering the setting mode of a certain parameter and together with the STEP push button for storing the set values. The different operations are described in the subsequent paragraphs in this manual.

Display

Display submenus

The measured and set values and the recorded data are shown on the display of the protection relay module. The display consists of four digits. The three green digits to the right show the measured, set or recorded value and the leftmost red digit shows the code number of the register. The measured or set value displayed is indicated by the adjacent yellow LED indicator on the front panel. When a recorded fault value is being displayed the red digit shows the number of the corresponding register. When the display functions as an operation indicator the red digit alone is shown.

When the auxiliary voltage of a protection relay module is switched on the module initially tests the display by stepping through all the segments of the display for about 15 seconds. At first the corresponding segments of all digits are lit one by one clockwise, including the decimal points. Then the center segment of each digit is lit one by one. The complete sequence is carried out twice. When the test is finished the display turns dark. The testing can be interrupted by pressing the STEP push button. The protection functions of the relay module are alerted throughout the testing.

Display main menu Any data required during normal operation are accessible in the main menu i.e. present measured values, present setting values and recorded parameter values.

The data to be shown in the main menu are sequentially called up for display by means of the STEP push button. When the STEP push button is pressed for about one second, the display moves forward in the display sequence. When the push button is pressed for about 0.5 seconds, the display moves backward in the display sequence.

From a dark display only forward movement is possible. When the STEP push button is pushed constantly, the display continuously moves forward stopping for a while in the dark position.

Unless the display is switched off by stepping to the dark point, it remains lit for about 5 minutes from the moment the STEP push button was last pushed. After the 5 minutes' time-out the dispaly is switched off.

Less important values and values not very often set are displayed in the submenus. The number of submenus varies with different relay module types. The submenus are presented in the description of the concerned protection relay module.

A submenu is entered from the main menu by pressing the PROGRAM push button for about one second. When the push button is released, the red digit of the display starts flashing, indicating that a submenu has been entered. Going from one submenu to another or back to the main menu follows the same principle as when moving from the main menu display to another;
the display moves forward when the STEP push button is pushed for one second and backward when it is pushed for 0.5 seconds. The main menu has been re-entered when the red display turns dark.

When a submenu is entered from a main menu of a measured or set value indicated by a LED indicator, the indicator remains lit and the address window of the display starts flashing. A submenu position is indicated by a flashing red address number alone on the dispaly without any lit set value LED indicator on the front panel.

Part of the settings and the selections of the operation characteristic of the relay modules in various applications are made with the selector switchgroups SG_ $_{-}$. The switchgroups are software based and thus not physically to be found in the hardware of the relay module. The indicator of the switchgroup is lit when the checksum of the switchgroup is shown on the display. Starting from the displayed checksum and by entering the setting mode, the switches can be set one by one as if they were real physical switches. At the end of the setting procedure, a checksum for the whole switchgroup is shown. The checksum can be used for verifying that the switches have been properly set. Fig. 2 shows an example of a manual checksum calculation.

When the checksum calculated according to the example equals the checksum indicated on the display of the relay module, the switches in the concerned switchgroup are properly set.

| Switch No | Pos. |  | Weigth |  | Value |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1 | X | 1 | = | 1 |
| 2 | 0 | X | 2 | = | 0 |
| 3 | 1 | X | 4 | = | 4 |
| 4 | 1 | x | 8 | = | 8 |
| 5 | 1 | x | 16 | = | 16 |
| 6 | 0 | X | 32 | $=$ | 0 |
| 7 | 1 | x | 64 | $=$ | 64 |
| 8 | 0 | X | 128 | = | 0 |
|  | Checksum |  | $\Sigma$ | $=$ | 93 |

Fig. 2. Example of calculating the checksum of a selector switchgroup SG_.

The functions of the selector switches of the different protection relay modules are described in detail in the manuals of the different relay modules.

## Settings

Setting mode

Most of the start values and operate times are set by means of the display and the push buttons on the front panel of the relay modules. Each setting has its related indicator which is lit when the concerned setting value is shown on the display.

In addition to the main stack of setting values most D type relay modules allow a second stack of settings. Switching between the main settings
and the second settings can be done in three different ways:

1) By command V150 over the serial communication bus
2) By an external control signal $\mathrm{BS} 1, \mathrm{BS} 2$ or RRES (BS3)
3) Via the push-buttons of the relay module, see submenu 4 of register $A$.

Generally, when a large number of settings is to be altered, e.g. during commissioning of relay systems, it is recommended that the relay settings are entered with the keyboard of a personal computer provided with the necessary software. When no computer nor software is available or when only a few setting values need to be altered the procedure described below is used.

The registers of the main menu and the submenus contain all parameters that can be set. The settings are made in the so called setting mode, which is accessible from the main menu or a submenu by pressing the PROGRAM push button, until the whole display starts flashing. This position indicates the value of the parameter before it has been altered. By pressing the PROGRAM push button the programming sequence moves forward one step. First the rightmost digit starts flashing while the rest of the display is steady. The flashing digit is set by means of the STEP push button. The flashing
cursor is moved on from digit to digit by pressing the PROGRAM push button and in each stop the setting is performed with the STEP push button. After the parameter values have been set, the decimal point is put in place. At the end the position with the whole display flashing is reached again and the data is ready to be stored.

A set value is recorded in the memory by pressing the push buttons STEP and PROGRAM simultaneously. Until the new value has been recorded a return from the setting mode will have no effect on the setting and the former value will still be valid. Furthermore any attempt to make a setting outside the permitted limits for a particular parameter will cause the new value to be disqualified and the former value will be maintained. Return from the setting mode to the main menu or a submenu is possible by pressing the PROGRAM push button until the green digits on the display stop flashing.

NOTE! During any local man-machine communication over the push buttons and the display on the front panel a five minute time-out function is active. Thus, if no push button has been pressed during the last five minutes, the relay returns to its normal state automatically. This means that the display turns dark, the relay escapes from a display mode, a programming routine or any routine going on, when the relay is left untouched. This is a convenient way out of any situation when the user does not know what to do.

Before a relay module is inserted into the relay case, one must assure that the module has been given the correct settings. If there however is
any doubt about the settings of the module to be inserted, the setting values should be read using a spare relay unit or with the relay trip circuits disconnected. If this cannot be done the relay can be sett into a non-tripping mode by pressing the PROGRAM push button and powering up the relay module simultaneously. The display will show three dashes "---" to indicate the nontripping mode. The serial communication is operative and all main and submenues are accessible. In the non-tripping mode unnecessary trippings are avoided and the settings can be checked. The normal protection relay mode is entered automatically after a timeout of five minutes or ten seconds after the dark display position of the main menu has been entered.


Fig.3. Basic principles of entering the main menus and submenus of a relay module.


Fig. 4.Example of part of the main and submenus for the settings of the overcurrent and earth-fault relay module SPCJ 4D29. The settings currently in use are in the main manu and they are displayed by pressing the STEP push button. The main menu also includes the measured current values, the registers $1 \ldots 9,0$ and A . The main and second setting values are located in the submenus and are called up on the display with the PROGRAM push button.

Operation in the setting mode. Manual setting of the main setting of the start current value I> of an overcurrent relay module. The initial value
a)

Press push button STEP repeatedly until the LED close to the I> symbol is lit and the current start value appears on the display.
b)

Enter the submenu to get the main setting value by pressing the PROGRAM push button more than one second and then releasing it. The red display digit now shows a flashing number 1 , indicating the first submenu position and the green digits show the set value.

## c)

Enter the setting mode by pressing the PROGRAM push button for five seconds until the display starts flashing.

## d)

Press the PROGRAM push button once again for one second to get the rightmost digit flashing.

## e)

Now the flashing digit can be altered. Use the STEP push button to set the digit to the desired value.

## f)

Press the PROGRAM push button to make the middle one of the green digits flash.

## g)

Set the middle digit with of the STEP push button.

## h)

Press the PROGRAM push button to make the leftmost green digit flash.
for the main setting is $0.80 \times \mathrm{I}_{\mathrm{n}}$ and for the second setting $1.00 \times \mathrm{I}_{\mathrm{n}}$. The desired main start value is $1.05 \mathrm{x}_{\mathrm{n}}$.

i)

Set the digit with the STEP push button.
j)

Press the PROGRAM push button to make the decimal point flash.

## k)

If needed, move the decimal point with the STEP push button.

## l)

Press the PROGRAM push button to make the whole display flash. In this position, corresponding to position c) above, one can see the new value before it is recorded. If the value needs changing, use the PROGRAM push button to alter the value.
m)

When the new value has been corrected, record it in the memory of the relay module by pressing the PROGRAM and STEP push buttons simultaneously. At the moment the information enters the memory, the green dashes flash once in the display, i.e. $1--$.
n)

Recording of the new value automatically initiates a return from the setting mode to the normal submenu. Without recording one can leave the setting mode any time by pressing the PROGRAM push button for about five seconds, until the green display digits stop flashing.
o)

If the second setting is to be altered, enter submenu position 2 of the setting $I>$ by pressing the STEP push button for approx. one second. The flashing position indicator 1 will then be replaced by a flashing number 2 which indicates that the setting shown on the display is the second setting for $I>$.

Enter the setting mode as in step c) and proceed in the same way. After recording of the requested values return to the main menu is obtained by pressing the STEP push button

until the first digit is switched off. The LED still shows that one is in the I> position and the display shows the new setting value currently in use by the relay module.

Operation in the setting mode. Manual setting of the main setting of the checksum for the switchgroup SGF1 of a relay module. The initial value for the checksum is 000 and the switches
a)

Press push button STEP until the LED close to the SGF symbol is lit and the checksum appears on the display.

## b)

Enter the submenu to get the main checksum of SGF1 by pressing the PROGRAM push button for more than one second and then releasing it. The red display now shows a flashing number 1 indicating the first submenu position and the green digits show the checksum.
c)

Enter the setting mode by pressing the PROGRAM push button for five seconds until the display starts flashing.

## d)

Press the PROGRAM push button once again to get the first switch position. The first digit of the display now shows the switch number. The position of the switch is shown by the rightmost digit.

## e)

The switch position can now be toggled between 1 and 0 by means of the STEP push button and it is left in the requested position 1.

## f)

When switch number 1 is in the requested position, switch number 2 is called up by pressing the PROGRAM push button for one second. As in step e), the switch position can be altered by using the STEP push button. As the desired setting for SGF1/2 is 0 the switch is left in the 0 position.

## g)

Switch SGF1/3 is called up as in step f) by pressing the PROGRAM push button for about one second.

SGF1/1 and SGF1/3 are to be set in position 1. This means that a checksum of 005 should be the final result.


The switch position is altered to the desired position 1 by pressing the STEP push button once.

i)

Using the same procedure the switches SGF 1/ 4 ... 8 are called up and, according to the example, left in position 0 .
j)

In the final setting mode position, corresponding to step c), the checksum based on the set switch positions is shown.

## k)

If the correct checksum has been obtained, it is recorded in the memory by pressing the push buttons PROGRAM and STEP simultaneously. At the moment the information enters the memory, the green dashes flash in the display, i.e. $1-$ - If the checksum is incorrect, the setting of the separate switches is repeated using the PROGRAM and STEP push buttons starting from step d ).
l)

Recording the new value automatically initiates a return from the setting mode to the normal menu. Without recording one can leave the setting mode any time by pressing the PROGRAM push button for about five seconds, until the green display digits stop flashing.

## m)

After recording the desired values return to the main menu is obtained by pressing the STEP push button until the first digit is turned off. The LED indicator SGF still shows that one is in the SGF position and that the display shows the new checksum for SGF1 currently in use by the relay module.


Recorded information

The parameter values measured at the moment when a fault occurs or at the trip instant are recorded in the registers. The recorded data, except for some parameters, are set to zero by pressing the push buttons STEP and PROGRAM simultaneously. The data in normal registers are erased if the auxiliary voltage supply to the relay is interrupted, only the set values and certain other essential parameters are maintained in non-volatile registers during a voltage failure.

The number of registers varies with different relay module types. The functions of the registers are illustrated in the descriptions of the different relay modules. Additionally, the system front panel of the relay contains a simplified list of the data recorded by the various relay modules of the protection relay.

All D type relay modules are provided with two general registers: register 0 and register A.

Register 0 contains, in coded form, the information about e.g. external blocking signals, status information and other signals. The codes are explained in the manuals of the different relay modules.

Register A contains the address code of the relay modul which is reqiured by the serial communication system.

Submenu 1 of register A contains the data transfer rate value, expressed in kilobaud, of the serial communication.

Submenu 2 of register A contains a bus communication monitor for the SPAbus. If the protection relay, which contains the relay module, is linked to a system including a contol data communicatoe, for instance SRIO 1000 M and the data communication system is operating, the counter reading of the monitor will be zero. Otherwise the digits $1 . . .255$ are continuously scrolling in the monitor.

Submenu 3 contains the password required for changing the remote settings. The address code, the data transfer rate of the serial communication and the password can be set manually or via the serial communication bus. For manual setting see example 1.

The default value is 001 for the address code, 9.6 kilobaud for the data transfer rate and 001 for the password.

In order to secure the setting values, all settings are recorded in two separate memory banks within the non-volatile memory. Each bank is complete with its own checksum test to verify the condition of the memory contents. If, for some reason, the contents of one bank is disturbed, all settings are taken from the other bank and the contents from here is transferred to the faulty memory region, all while the relay is in full operation condition. If both memory banks are simultaneously damaged the relay will be be set out of operation, and an alarm signal will be given over the serial port and the IRF output relay

Register 0 also provides access to a trip test function, which allows the output signals of the relay module to be activated one by one. If the auxiliary relay module of the protection assembly is in place, the auxiliary relays then will operate one by one during the testing.

When pressing the PROGRAM push button for about five seconds, the green digits to the right start flashing indicating that the relay module is in the test position. The indicators of the settings indicate by flashing which output signal can be activated. The required output function is selected by pressing the PROGRAM push button for about one second.

The indicators of the setting quantities refer to the following output signals:

Setting I> Starting of stage I>
Setting t> Tripping of stage I>
Setting I>> Starting of stage I>>
Setting t>> Tripping of stage I>>
etc.
No indication

The selected starting or tripping is activated by simultaneous pressing of the push buttons STEP and PROGRAM. The signal remains activated as long as the two push butttons are pressed. The effect on the output relays depends on the configuration of the output relay matrix switches.

The self-supervision output is activated by pressing the STEP push button 1 second when no setting indicator is flashing. The IRF output is activated in about 1 second after pressing of the STEP push button.

The signals are selected in the order illustrated in Fig. 4.


Fig. 5.Sequence order for the selection of output signals in the Trip test mode

If, for instance, the indicator of the setting $\mathrm{t}>$ is flashing, and the push buttons STEP and PROGRAM are being pressed, the trip signal from the low-set overcurrent stage is activated. Return to the main menu is possible at any stage of the trip test sequence scheme, by pressing the PROGRAM push button for about five seconds.

Note!
The effect on the output relays then depends on the configuration of the output relay matrix switchgroups SGR 1...3.

Trip test function. Forced activation of the outputs.
a)

Step forward on the display to register 0 .

b)

Press the PROGRAM push button for about five seconds until the three green digits to the right.

c)

Hold down the STEP push button. After one second the red IRF indicator is lit and the IRF
 output is activated. When the step push button is released the IRF indicator is switched off and the IRF output resets.

## d)

Press the PROGRAM push button for one second and the indicator of the topmost setting start flashing.
e)

If a start of the first stage is required, now press the push-buttons PROGRAM and STEP simultaneously. The stage output will be activated and the output relays will operate according to the actual programming of the relay output switchgroups SGR.

f)

To proceed to the next position press the PROGRAM push button for about 1 second until the indicator of the second setting starts flashing.


## g)

Press the push buttons PROGRAM and STEP simultaneously to activate tripping of stage 1 (e.g. the I> stage of the overcurrent module SPCJ 4D29). The output relays will operate according to the actual programming of the relay switchgroups SGR. If the main trip relay is operated the trip indicator of the measuring module is lit.

h)

The starting and tripping of the remaining stages are activated in the same way as the first stage above. The indicator of the corresponding setting starts flashing to indicate that the concerned stage can be activated by pressing the STEP and PROGRAM buttons simultaneously. For any forced stage operation, the output relays will respond according to the setting of the relay output switchgroups SGR. Any time a certain stage is selected that is not wanted to operate, pressing the PROGRAM button once more will pass by this position and move to the next one without carrying out any operation of the selected stage.


It is possible to leave the trip test mode at any step of the sequence scheme by pressing the PROGRAM push button for about five seconds until the three digits to the right stop flashing.

A relay module is provided with a multiple of separate operation stages, each with its own operation indicator shown on the display and a common trip indicator on the lower part of the front plate of the relay module.

The starting of a relay stage is indicated with one number which changes to another number when the stage operates. The indicator remains glowing although the operation stage resets. The
indicator is reset by means of the RESET push button of the relay module. An unreset operation indicator does not affect the function of the protection relay module.

In certain cases the function of the operation indicators may deviate from the above principles. This is described in detail in the descriptions of the separate modules.

## Fault codes

In addition to the protection functions the relay module is provided with a self-supervision system which continuously supervises the function of the microprocessor, its program execution and the electronics.

Shortly after the self-supervision system detects a permanent fault in the relay module, the red IRF indicator on the front panel is lit. At the same time the module puts forward a control signal to the output relay of the self-supervision system of the protection relay.

In most fault situations a fault code, indicating the nature of the fault, appears on the display of
the module. The fault code, which consists of a red figure " 1 " and a three digit green code number, cannot be removed from the display by resetting. When a fault occurs, the fault code should be recorded and stated when service is ordered. When in a fault mode, the normal relay menus are operative, i.e. all setting values and measured values can be accessed although the relay operation is inhibited. The serial communication is also operative making it possible to access the relay information also from a remote site. The internal relay fault code shown on the display remains active until the internal fault possibly disappears and can also be remotely read out as variable V 169 .

## SPCJ 4D29

## Overcurrent and earth-fault relay module

User's manual and Technical description

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## Features

Low-set phase overcurrent stage I> with definite time or inverse time characteristic

High-set phase overcurrent stage I>> with instantaneous function or definite time characteristic

Low-set earth-fault stage $\mathrm{I}_{0}>$ with definite time or inverse time characteristic

High-set earth-fault stage $\mathrm{I}_{0} \gg$ with definite time characteristic

Six time/current curve sets at inverse time characteristic of the overcurrent stage $\mathrm{I}>$ and the earth-fault stage $\mathrm{I}_{0}>$

Digital display of measured and set values and data sets recorded at the moment of relay operation

Parametrization of the module by push-buttons on the front panel or via the serial port using a portable PC and a suitable software

Continuous hardware and software supervision including auto-diagnosis

## Description of function

Phase overcurrent unit

The phase overcurrent unit of the relay module SPCJ 4D29 is designed for single-phase, twophase or three-phase overcurrent protection. It includes two overcurrent stages, i.e. a low-set overcurrent stage $\mathrm{I}>$ and a high-set overcurrent stage I>>.

The low-set or high-set phase overcurrent stage starts if the current on one or several of the phases exceeds the set start current value of the stage concerned. When the stage starts it generates a start signal SS1 or TS1 and simultaneously the digital display on the front panel indicates starting. If the overcurrent situation lasts long enough to exceed the set operate time, the stage operates and generates a trip signal TS2. At the same time the operation indicator is lit with red light. The red operation indicator remains lit although the stage resets. The indicator is reset by pushing the RESET push-button. By proper configuration of the output relay switchgroups an additional auxiliary trip signal TS1 can be obtained.

The operation of the low-set phase overcurrent stage I> or the high-set phase overcurrent stage I>> can be blocked by routing a blocking signal BS to the unit. The blocking configuration is set with switchgroup SGB.

The operation of the low-set phase overcurrent stage can be based on definite time or inverse time characteristic. The operation characteristic is selected with the SGF1/1...3 switches. At definite time operation characteristic the operate time $\mathrm{t}>$ is set in seconds within the range, $0.05 \ldots 300 \mathrm{~s}$. When the inverse time operation characteristic (IDMT) is selected, four internationally standardized and two complementary time/current curves are available. The selector switches SGF1/1... 3 are also used for selecting the desired operation characteristic.

Note!
The maximum continuous current carrying capacity of the energizing inputs is $4 \times \mathrm{I}_{\mathrm{n}}$, which must be observed when relay settings are calculated.

Note!
At inverse time characteristic the effective setting range of the low-set overcurrent stage is $0.5 \ldots 2.5 \times \mathrm{I}_{\mathrm{n}}$, although start current settings within the range $2.5 \ldots 5.0 \mathrm{xI}_{\mathrm{n}}$ can be set on the relay. At inverse time characteristic any start current setting above $2.5 \times \mathrm{I}_{\mathrm{n}}$ of the low-set stage will be regarded as being equal to $2.5 \mathrm{xI}_{\mathrm{n}}$.

Note!
The operation of the low-set stage based on inverse time characteristic will be blocked by starting of the high-set stage. Then the operate time of the overcurrent unit is determined by the set operate time of the high-set stage at heavy fault currents.

The setting range of the operate time $t \gg$ of the high-set phase overcurrent stage is $0.04 \ldots 300 \mathrm{~s}$.

The operate signal of the two overcurrent stages is provided with a latching feature (switch SGB/6) which means that the operate signal TS2 is kept high after an operation, although the overcurrent stage resets. The latched TS2 signal is reset by pushing the RESET and PROGRAM push-buttons simultaneously or via the serial port using the command V101, see also chapter "Selector switches".

The set start current value I>> of the high-set phase overcurrent stage can be doubled automatically on connection of the protected object to the network, i.e. at starting. In this way the start current of the high-set phase overcurrent stage can be given a lower value than the level of the connection inrush current. The automatic doubling function is selected with switch SGF1/5. The starting, which activates the doubling function, is defined as a situation where the phase currents rise from a value below $0.12 \times \mathrm{I}>$ to a value exceeding $1.5 \mathrm{xI}>$ in less than 60 ms . The function stops when the currents fall below 1.25 x I>.

The setting range of the start current of the highset phase overcurrent stage is $0.5 \ldots 40 \times \mathrm{I}_{\mathrm{n}}$. When the high-set stage is given a start current setting in the lower end of the setting range, the relay module will contain two almost identical overcurrent stages. This enables the overcurrent unit of the SPCJ 4D29 module to be used, for example, in two-stage load shedding applications.

The high-set phase overcurrent stage can be set out of operation with switch SGF2/5. When the high-set stage is set out of operation the display shows "- --", indicating that the start current setting is infinite.

Circuit breaker
failure protection unit

Remote setting

The non-directional earth-fault unit of the relay module SPCJ 4D29 is a single-pole earth-fault unit. It contains two earth-fault stages, i.e. a low-set earth-fault stage $\mathrm{I}_{0}>$ and a high-set earthfault stage $\mathrm{I}_{0} \gg$.

The low-set or high-set earth-fault stage starts, if the measured current exceeds the set start current value. When the stage starts it generates a start signal SS1 or TS1 and simultaneously the digital display on the front panel indicates starting. If the earth-fault situation lasts long enough to exceed the set operate time, the stage operates and generates a trip signal TS2. At the same time the operation indicator TRIP is lit with red light. The red operation indicator remains lit although the stage resets. The indicator is reset by pushing the RESET push-button. By proper configuration of the output relay switchgroups an additional auxiliary trip signal TS1 can be obtained.

The operation of the low-set earth-fault stage $\mathrm{I}_{0}>$ or the high-set earth-fault stage $\mathrm{I}_{0} \gg$ can be blocked by routing a blocking signal BS to the earth-fault unit. The blocking configuration is set with switchgroup SGB.

The operation of the low-set earth-fault stage can be based on definite time or inverse time characteristic. The operation characteristic is selected with the SGF/6... 8 switches. At definite time operation characteristic the operate time $t_{0}>$ is directly set in seconds within the
range, $0.05 \ldots 300 \mathrm{~s}$. When the inverse time operation characteristic (IDMT) is selected, four internationally standardized and two complementary time/current curves are available. The selector switches SGF1/ $6 \ldots 8$ are also used for selecting the desired operation characteristic.

The setting range of the operate time $t_{0} \gg$ of the high-set earth-fault stage is $0.05 \ldots 300 \mathrm{~s}$.

## Note!

The operation of the low-set stage based on inverse time characteristic will be blocked by starting of the high-set stage. Then the operate time of the earth-fault unit is determined by the set operate time of the high-set stage at heavy fault currents.

The operate signal of the two earth-fault stages is provided with a latching feature (switch SGB/7) which means that the operate signal TS2 is kept high after an operation, although the earth-fault stage resets. The TS2 signal is reset by pushing the RESET and PROGRAM push-buttons simultaneously or via the serial port using the command V101, see chapter "Selector switches", page 9 .

The high-set earth-fault stage can be set out of operation with switch SGF2/6. When the highset stage is set out of operation the display shows "---", indicating that the start current setting is infinite.

The relay module features a circuit breaker failure protection (CBFP) unit. The CBFP unit generates a trip signal via TS1 after a set operate time $0.1 \ldots 1 \mathrm{~s}$, following the main trip signal TS2, if the fault has not been cleared before the set operate time has elapsed. The output contact of the CBFP unit is normally used for tripping
an upstream circuit breaker. The CBFP unit can also be used for tripping via redundant trip circuits of the same circuit breaker, if the circuit breaker is provided with two trip coils. The circuit breaker failure protection unit is alerted/ set out of operation with switch SGF1/4.

The relay can be given two sets of setting values, the main settings and the second settings. Switching between main settings and second settings can be done in three different ways, i) with a
command V150 via the serial port, ii) with a command via the external control input BS or manually by changing a parameter in submenu 4 of register A.


Fig. 1. Block diagram for the combined overcurrent and earth-fault relay module SPCJ 4D29.

| $\mathrm{I}_{\text {L1 }}, \mathrm{I}_{\text {L2 }}, \mathrm{I}_{\text {L3 }}$ | Energizing currents <br> Residual current |
| :--- | :--- |
| $\mathrm{I}_{0}$ | ES |
| External control signal |  |
| SGF1...2 | Seletor switchgroup SGF for operational relay functions |
| SGB | Selector switchgroup SGB for special relay functions |
| SGR1...3 | Selector switchgroups SGR for configuration of output relays |
| TS1 | Start signal 1 or auxiliary trip signal configured with switchgroup SGR3 |
| SS1 | Start signal configured with switchgroup SGR1 |
| SS2 | Trip signal 1 conffigured with switchgroup SGR2 |
| SS3 | Trip signal 2 configured with switchgroup SGR2 |
| TS2 | Trip signal configured with switchgroup SGR1 |
| AR1, AR2, AR3 | Start signals to possible external optional auto-reclose relays |
| TRIP | Red operation (trip) indicator |

Note!
All input and output signals of the relay module are not necessarily wired to the terminals of a particular relay. The signals wired to the termi-
nals of a particular protection relay are shown in the signal diagram in the general part of the relay manual.

Indicators for the measured phase currents $\mathrm{I}_{\mathrm{L} 1}, \mathrm{I}_{\mathrm{L} 2}, \mathrm{I}_{\mathrm{L} 3}$ and the residual current $\mathrm{I}_{0}$

Indicator for the start current of the I> stage Indicator for the operate time $\mathrm{t}>$ or time multiplier k of the I> stage
Indicator for the start current of the $\mathrm{I} \gg$ stage Indicator for the operate time of the $\mathrm{I} \gg$ stage Indicator for the start current of the $\mathrm{I}_{0}>$ stage Indicator for the operate time $\mathrm{t}_{0}>$ or time multiplier $\mathrm{k}_{0}$ of the $\mathrm{I}_{0}>$ stage
Indicator for the start current of the $\mathrm{I}_{0} \gg$ stage
Indicator for the operate time of the $\mathrm{I}_{0} \gg$ stage
Indicator for the checksum of switchgroups SGF1... 2
Indicator for the checksum of switchgroup SGB
Indicator for the checksum of switchgroups SGR1... 3


Relay module symbol

Self-supervision alarm indicator

Digital display

Reset and display step push-button

Selector push-button

TRIP indicator

Type designation of the module

Fig. 2. Front panel of the combined overcurrent and earth-fault relay module SPCJ 4D29.

Both overcurrent stages have their own start indicators and operation indicators shown as figures on the digital display. Further, all the protection stages share a common red LED indicator marked "TRIP" which is located in the lower right corner of the front panel and which is lit on operation of a stage.

The figure on the display indicating starting or operation remains lit when the current stage resets, thus indicating which protection stage
has operated. The start or operation indicators are reset by pushing the RESET push-button. The function of the relay module is not affected by an unreset indicator. If the starting of a stage is short enough not to cause an operation of the relay, the start indication is normally self-reset when the stage resets. By means of switches SGF2/1... 4 the start indicators can be configured for manual resetting. The following table shows a guide to the start and trip indicators of the relay module.

| Indication | Explanation |  |
| :---: | :---: | :---: |
| 1 | I $>$ START | = the low-set stage $\mathrm{I}>$ of the overcurrent unit has started |
| 2 | I > TRIP | $=$ the low-set stage $\mathrm{I}>$ of the overcurrent unit has operated |
| 3 | I $\gg$ START | $=$ the high-set stage $\mathrm{I} \gg$ of the overcurrent unit has started |
| 4 | I >> TRIP | $=$ the high-set stage $\mathrm{I} \gg$ of the overcurrent unit has operated |
| 5 | $\mathrm{I}_{0}>$ START | $=$ the low-set stage $\mathrm{I}_{0}>$ of the earth-fault unit has started |
| 6 | $\mathrm{I}_{0}>$ TRIP | $=$ the low-set stage $\mathrm{I}_{0}>$ of the earth-fault unit has operated |
| 7 | $\mathrm{I}_{0} \gg$ START | $=$ the high-set stage $\mathrm{I}_{0} \gg$ of the earth-fault unit has started |
| 8 | $\mathrm{I}_{0} \gg$ TRIP | $=$ the high-set stage $\mathrm{I}_{0} \gg$ of the earth-fault unit has operated |
| 9 | CBFP | = the circuit breaker failure protection has operated |

When one of the protection stages of the relay module operates, the indicators for the energizing current of the module show the faulty phase, i.e. in which phase(s) the current has exceeded the set start value of the stage (so called phase fault indication). If, for instance, the operation indicator " 2 " of the low-set stage is lit, as are the indicators $\mathrm{I}_{\mathrm{L} 1}$ and $\mathrm{I}_{\mathrm{L} 2}$ also, the relay operation has been caused by overcurrent on the L1 and L2 phases. The fault indications are reset by pushing the RESET push-button.

The self-supervision alarm indicator IRF indicates, when lit, that the self-supervision system has detected a permanent internal relay fault. The indicator is lit with red light shortly after a fault has been detected. At the same time the relay module generates a control signal to the output relay of the self-supervision system IRF. Additionally, in most fault cases, an auto-diagnostic fault code showing the nature of the fault appears on the display. The fault code, consists of a red figure one (1) and a green code number. When a fault code is obtained it should be recorded for statistical and maintenance purposes.

The setting values are shown by the right-most three digits of the display. When lit, the LED indicators on the front panel adjacent to the
symbol of the setting quantity shows the quantity currently being displayed.


Further, the checksums of switchgroups SGF1, SGB and SGR1 are shown on the display when the indicators adjacent to the switchgroup symbols on the front panel are lit. The checksums for switchgroups SGF2, SGR2 and SGR3 are found in the submenus under the main menu of
the first switchgroup. For further information, see chapter "Menus and registers". An example of how the checksum can be calculated manually is given in manual "General characteristics of $D$ type relay modules..

Additional functions required in various applications are selected with switchgroups SGF, SGB and SGR indicated on the front panel. The numbering of the switches, $1 \ldots 8$, and the switch positions 0 and 1 are shown when the switch-
groups are set. Under normal service conditions only the checksums are shown. Switchgroups SGF2, SGR2 and SGR3 are found in the submenus of the main menus of switchgroups SGF and SGR.

Function switchgroup SGF1

| Switch | Function |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| SGF1/1 <br> SGF1/2 <br> SGF1/3 | Switches SGF1/1... 3 are used for selecting the characteristic of the low-set overcurrent stage I>, i.e. definite time operation characteristic or inverse definite minimum time (IDMT) characteristic. At IDMT characteristic the switches are also used for selecting the required current/time characteristic for the stage. |  |  |  |  |
|  | SGF1/1 | SGF1/2 | SGF1/3 | Characteristic | Time or curve set |
|  | 0 1 0 1 0 1 | 0 1 1 0 0 1 | 0 0 0 | Definite time IDMT IDMT IDMT IDMT IDMT IDMT --- | 0.05... 300 s <br> Extremely inverse <br> Very inverse <br> Normal inverse <br> Long-time inverse <br> RI-characteristic RXIDG-characteristic <br> (Long-time inverse) |
| SGF1/4 | Circuit breaker failure protection (CBFP). |  |  |  |  |
|  | When SGF1/4 = 1 the trip signal TS2 will start a timer which will generates a delayed operate signal via TS1, if the fault has not been cleared before the operate time has elapsed. <br> When switch SGF1/4 = 0 the circuit breaker failure protection is out of operation. |  |  |  |  |
| SGF1/5 | When SGF1/5 $=0$, no doubling of the start current setting of stage $\mathrm{I} \gg$ is obtained. When SGF $1 / 5=1$, the start current setting of stage $\mathrm{I} \gg$ doubles automatically. The doubling feature makes it possible to give the high-set stage a setting value below the connection inrush current level. |  |  |  |  |
| SGF1/6 <br> SGF1/7 <br> SGF1/8 | Switches SGF1/6... 8 are used for selecting the operation characteristic of the low-set earth-fault stage $\mathrm{I}_{0}>$, i.e. definite time characteristic or inverse definite minimum time (IDMT) characteristic. At inverse definite minimum time characteristic the switches are also used for selecting the current/time characteristic of the stage. |  |  |  |  |
|  | SGF1/6 | SGF1/7 | SGF1/8 | Characteristic | Time or curve |
|  | 0 | 0 | 0 | Definite time | 0.05... 300 s |
|  | 1 | 0 | 0 | IDMT | Extremely inverse |
|  | 0 | 1 | 0 | IDMT | Very inverse |
|  | 1 | 1 | 0 | IDMT | Normal inverse |
|  | 0 | 0 | 1 | IDMT | Long-time inverse |
|  | 1 | 0 | 1 | IDMT | RI-characteristic |
|  | 0 | 1 | 1 | IDMT | RXIDG-characteristic |
|  | 1 | 1 | 1 | IDMT | Not in use (long-time inverse) |

On delivery from the factory all switches SGF1 are set at zero, i.e. the checksum for SGF1 is 0 .

Function switchgroup SGF2

| Switch | Function |
| :--- | :--- |
| SGF2/1 | Switches SGF2/1...4 are used for selecting the operation characteristic of the start |

SGF2/2 indicators of the different stages. When the switches are in position 0 the start signals
SGF2/3 are all automatically reset when the fault is cleared. To give the indicator of a stage the
SGF2/4 hand reset mode of operation, the corresponding switch is set in position 1:
SGF2/1 = 1 equals manual reset mode for the start indication of stage I>
SGF2/2 $=1$ equals manual reset mode for the start indication of stage $\mathrm{I} \gg$ SGF2/3 = 1 equals manual reset mode for the start indication of stage $I_{0}>$ SGF2/4 = 1 equals manual reset mode for the start indication of stage $\mathrm{I}_{0} \gg$

SGF2/5 Operation of the high-set phase overcurrent stage I>>.
When SGF2/5 $=0$ the high-set stage $\mathrm{I} \gg$ is alerted When SGF2/5 = 1 the high-set stage $\mathrm{I} \gg$ is out of operation and the display shows "- - -"

SGF2/6 Operation of the high-set earth-fault stage $\mathrm{I}_{0} \gg$.
When SGF2/6 $=0$ the high-set stage $\mathrm{I}_{0} \gg$ is alerted When SGF2/6 = 1 the high-set stage $\mathrm{I}_{0} \gg$ is out of operation and the display shows "- - -"

SGF2/7 Start signal of the high-set stage I>> to the auto-reclose signal output AR1. When SGF2/7 = 1 , the start signal of the I>> stage is routed to output AR1.

Note! Outputs AR1 and SS3 are interconnected and they always carry the same signal. Therefore, if AR1 is used for starting auto-reclose functions, SS3 cannot be used for any other purpose.

When SGF2/7 =0, the start signal of the I>> stage is not routed to output AR1 nor SS3. Thus the signal output SS3 is available for other purposes.

SGF2/8 Start signal of the low-set stage $\mathrm{I}_{0}>$ or high-set stage $\mathrm{I}_{0} \gg$ to auto-reclose signal output AR3.

When $\mathrm{SGF} 2 / 8=0$ the start signal from the $\mathrm{I}_{0}>$ stage is routed to output AR3 When SGF2/8 = 1 the start signal from the $\mathrm{I}_{0} \gg$ stage is routed to output AR3

When the relay is delivered from the factory the SGF2 switches are set at zero, i.e. the checksum for SGF2 is 0 .

Blocking or control signal configuration switchgroup SGB

| Switch | Function |
| :---: | :---: |
| $\begin{aligned} & \mathrm{SGB} / 1 \\ & \mathrm{SGB} / 2 \\ & \mathrm{SGB} / 3 \\ & \mathrm{SGB} / 4 \end{aligned}$ | Switches SGB/1... 4 are used for routing an external blocking signal BS to one or more of the protection stages of the relay module. When the switches all are in position 0 no stage is blocked. <br> When SGB/1 = 1 the I> stage is blocked by the external control signal BS <br> When $\mathrm{SGB} / 2=1$ the $\mathrm{I} \gg$ stage is blocked by the external control signal BS <br> When $\mathrm{SGB} / 3=1$ the $\mathrm{I}_{0}>$ stage is blocked by the external control signal BS <br> When $S G B / 4=1$ the $I_{0} \gg$ stage is blocked by the external control signal $B S$ |
| SGB/5 | Selection of main settings or second settings with an external control signal BS or via the serial interface using command V150. <br> When $\mathrm{SGB} / 5=0$ the settings can be controlled via the serial port but not via the external control input BS <br> When $S G B / 5=1$, the settings can be controlled via the external control input. The main values are enforced when the control input is not energized and the second settings are enforced when the control input is energized. <br> Note! When the application includes switching between main and second settings, it should be noted that switch SGB/5 must have the same position in the main set of settings and the second set of settings. Otherwise a conflict situation might occur when the settings are switched by external control or via the serial port. |
| SGB/6 | Latching of the trip signal TS2 of the phase overcurrent unit. <br> When SGB/6 $=0$ the trip signal returns to its initial state (= the output relay drops off), when the energizing signal causing the operation falls below the set start current. When $\mathrm{SGB} / 6=1$ the trip signal is latched (= the output relay remains picked up after operation), although the energizing signal falls below the start current. The trip signal is to be manually reset by pushing the push-buttons RESET and PROGRAM simultaneously. ${ }^{1}$ |
| SGB/7 | Latching of the trip signal TS2 of the earth-fault unit. <br> When SGB/7 $=0$ the trip signal returns to its initial state (= the output relay drops off), when the measuring signal causing the operation falls below the set start current. When $\mathrm{SGB} / 7=1$ the trip signal is latched (= the output relay remains picked up after operation), although the energizing signal falls below the start current. The trip signal is to be manually reset by pushing the push-buttons RESET and PROGRAM simultaneously. ${ }^{1)}$ |
| SGB/8 | Remote resetting of a latched output relay and memorized values. <br> When the output TS2 has been given the latching mode with switch SGB/6 or SGB/7, a remote reset can be performed using the external control input $B S$, when switch $S G B / 8=1$. |

When the relay is delivered from the factory the SGB switches are set at zero, i.e. the checksum for $S G B$ is 0 .
${ }^{1)}$ From the program versions 037 F or 056 A and later versions an additional feature has been incorporated into the relay module SPCJ 4 D 29 . When the latching function is used the latched output can be reset by pushing the PROGRAM button alone, in which case the stored information of the module is not erased.

Output relay matrix switchgroups SGR1, SGR2 and SGR3

SGR1 The switches of switchgroup SGR1 are used to select the start and operate signals to be routed to outputs SS1 and TS2.

SGR2 The switches of switchgroup SGR2 are used for routing the operate signals of the protection stages to the outputs SS2 and SS3.

SGR3 The switches of switchgroup SGR3 are used to route the start and operate signals to the start or auxiliary trip output TS1. Note! If the circuit breaker failure protection has been taken in use with switch SGF1/4, it will also occupy the TS1 output.

| Switch number | Function | Factory setting | Checksum value |
| :---: | :---: | :---: | :---: |
| SGR1/1 | When SGR1/1 = 1 , the start signal of the $\mathrm{I}>$ stage is routed to SS1 | 1 | 1 |
| SGR1/2 | When SGR1/2 = 1 , the operate signal of the I> stage is routed to TS2 | 1 | 2 |
| SGR1/3 | When SGR1/3 = 1, the start signal of the I>> stage is routed to SS1 | 0 | 4 |
| SGR1/4 | When SGR $1 / 4=1$, the operate signal of the $\mathrm{I} \gg$ stage is routed to TS2 | 1 | 8 |
| SGR1/5 | When SGR1/5 = 1 , the start signal of the $\mathrm{I}_{0}>$ stage is routed to SS1 | 0 | 16 |
| SGR1/6 | When SGR1/6 = 1 , the operate signal of the $\mathrm{I}_{0}>$ stage is routed to TS2 | 1 | 32 |
| SGR1/7 | When SGR1/7 = 1 , the staring signal of the $\mathrm{I}_{0} \gg$ stage is routed to SS1 | 0 | 64 |
| SGR1/8 | When SGR1/8 = 1 , the operate signal of the $\mathrm{I}_{0} \gg$ stage is routed to TS2 | 1 | 128 |
| Checksum for the factory settings of switchgroup SGR1 |  |  | 171 |


| SGR2/1 | When SGR2/1 = 1 , the operate signal of the $\mathrm{I}>$ stage is routed to SS2 | 1 | 1 |
| :---: | :---: | :---: | :---: |
| SGR2/2 | When SGR2/2 $=1$, the operate signal of the $\mathrm{I}>$ stage is routed to SS3 | 0 | 2 |
| SGR2/3 | When SGR2/3 = 1 , the operate signal of the I>> stage is routed to SS2 | 1 | 4 |
| SGR2/4 | When SGR2/4=1, the operate signal of the I>> stage is routed to SS3 | 0 | 8 |
| SGR2/5 | When SGR2/5 = 1 , the operate signal of the $\mathrm{I}_{0}>$ stage is routed to SS2 | 0 | 16 |
| SGR2/6 | When SGR2/6 $=1$, the operate signal of the $\mathrm{I}_{0}>$ stage is routed to SS3 | 1 | 32 |
| SGR2/7 | When SGR2/7 = 1 , the operate signal of the $\mathrm{I}_{0} \gg$ stage is routed to SS2 | 0 | 64 |
| SGR2/8 | When SGR2/8 = 1 , the operate signal of the $\mathrm{I}_{0} \gg$ stage is routed to SS3 | 1 | 128 |
| Checksum for the factory settings of switchgroup SGR2 |  |  | 165 |


| Switch number | Function | Factory setting | Checksum value |
| :---: | :---: | :---: | :---: |
| SGR3/1 | When SGR3/1 = 1 , the start signal of the $\mathrm{I}>$ stage is routed to TS1 | 0 | 1 |
| SGR3/2 | When SGR3/2 = 1 , the trip signal of the I> stage is routed to TS1 | 0 | 2 |
| SGR3/3 | When SGR3/3 = 1, the start signal of the I>> stage is routed to TS1 | 0 | 4 |
| SGR3/4 | When SGR3/4 = 1, the trip signal of the I>> stage is routed to TS1 | 0 | 8 |
| SGR3/5 | When SGR3/5 = 1 , the start signal of the $\mathrm{I}_{0}>$ stage is routed to TS1 | 0 | 16 |
| SGR3/6 | When SGR3/6 $=1$, the trip signal of the $\mathrm{I}_{0}>$ stage is routed to TS1 | 0 | 32 |
| SGR3/7 | When SGR3/7 = 1 , the start signal of the $\mathrm{I}_{0} \gg$ stage is routed to TS1 | 0 | 64 |
| SGR3/8 | When SGR3/8 $=1$, the trip signal of the $\mathrm{I}_{0} \gg$ stage is routed to TS1 | 0 | 128 |
| Checksum for the factory settings of switchgroup SGR3 |  |  | 0 |

## Measured data

The measured current values are shown by the three right-most digits of the display. The value
displayed at the present time is indicated by a LED indicator on the front panel.

| Indicator | Measured data |
| :---: | :---: |
| $\mathrm{I}_{\text {L1 }}$ | Line current on phase L1 as a multiple of the rated current $I_{n}$ of the used energizing input ( $0 \ldots 63 \times \mathrm{I}_{\mathrm{n}}$ ). |
| $\mathrm{I}_{\mathrm{L} 2}$ | Line current on phase L2 as a multiple of the rated current $I_{n}$ of the used energizing input ( $0 \ldots 63 \times \mathrm{I}_{\mathrm{n}}$ ). |
| $\mathrm{I}_{\text {L3 }}$ | Line current on phase L3 as a multiple of the rated current $I_{n}$ of the used energizing input ( $0 \ldots . .63 \times \mathrm{I}_{\mathrm{n}}$ ). |
| $\mathrm{I}_{0}$ | Residual current as a multiple of the rated current $I_{n}$ of the used energizing input ( $0 \ldots 21 \times \mathrm{I}_{\mathrm{n}}$ ). |

Recorded information

The left-most red digit shows the address of the register and the right-most three digits the recorded value.

The // symbol in the text indicates that the item following the symbol is found in a submenu.

| Register/ <br> STEP | Recorded information |
| :---: | :--- |
| 1 | Phase current $\mathrm{I}_{\mathrm{L}}$. displayed as a multiple of the rated current of the used input of the <br> overcurrent unit. If the overcurrent unit starts or operates, the current value at the <br> moment of operation is recorded in a memory stack. Any new operation adds a new <br> value to the stack and moves the old values one place forward. Five values are <br> memorized. If a sixth value is recorded the oldest value is lost. |

2 Phase current $\mathrm{I}_{\mathrm{L} 2}$ measured as a multiple of the rated current of the used input of the overcurrent unit. If the overcurrent unit starts or operates, the current value at the moment of operation is recorded in a memory stack. Any new operation adds a new value to the stack and moves the old values one place forward. Five values are memorized. If a sixth value is recorded, the oldest value is lost.

Phase current $\mathrm{I}_{\mathrm{L} 3}$ measured as a multiple of the rated current of the used input of the overcurrent unit. If the overcurrent unit starts or operates, the current value at the moment of operation is recorded in a memory stack. Any new operation adds a new value to the stack and moves the old values one place forward. Five values are memorized. If a sixth value is recorded, the oldest value is lost.

Maximum demand current value for a period of 15 minutes expressed in multiples of the rated current $I_{n}$ of the used energizing input and based on the highest phase current. // Highest maximum demand current value recorded after the last relay reset.

Duration of the last start situation of the $\mathrm{I}>$ stage as a percentage of the set operate time $t>$ or at IDMT characteristic the calculated operate time. At any new start the time counter starts from zero. Five start times are memorized. If a sixth start occurs the oldest start time is lost. When the concerned stage has operated, the counter reading is 100 . // Number of starts of the low-set overcurrent stage $\mathrm{I}>, \mathrm{n}(\mathrm{I}>)=$ $0 . . .255$.

Duration of the last start situation of the I>> stage as a percentage of the set operate time $t \gg$. At any new start the time counter starts from zero. Five start times are memorized. If a sixth start occurs the oldest start time is lost. When the concerned stage has operated, the counter reading is 100 . // Number of starts of the high-set overcurrent stage I>>, n (I>>) $=0 . . .255$.

Neutral current $\mathrm{I}_{0}$ displayed as a multiple of the rated current of the used energizing input of the earth-fault unit. If the earth-fault unit starts or operates, the current value at the moment of operation is recorded in a memory stack. Any new operation adds a new value to the memory stack and moves the old values forward one place. Five values are memorized - if a sixth value is recorded, the oldest value will be lost.

Duration of the latest start situation of stage $\mathrm{I}_{0}>$ as a percentage of the set operate time $\mathrm{t}_{0}>$ or in IDMT operation characteristic the calculated operate time. At any new start the time counter starts from zero. Five start times are memorized. If a sixth start is recorded the oldest start time is lost. When the concerned stage has operated, the counter reading is 100 . // Number of starts of the high-set overcurrent stage I>>, n $(\mathrm{I} \gg)=0 . . .255$.
$9 \quad$ Duration of the latest start situation of stage $\mathrm{I}_{0} \gg$ as a percentage of the set operate time $\mathrm{t}_{0} \gg$. At any new start the time counter starts from zero. Five start times are memorized. If a sixth start is recorded the oldest start time will be lost. When the concerned stage has operated, the counter reading is 100 .// Number of starts of the high-set earth-fault stage $\mathrm{I}_{0} \gg, \mathrm{n}\left(\mathrm{I}_{0} \gg\right)=0 \ldots 255$.

| Register/ STEP | Recorded information |
| :---: | :---: |
| 0 | Display of blocking signals and other external control signals. <br> The right-most digit indicates the state of the blocking input of the module. The following states may be indicated: <br> $0=$ no blocking signal <br> $1=$ blocking or control signal BS active. <br> The function of the external control signal on the relay unit is determined by the settings of switchgroup SGB <br> From register " 0 " the TEST mode can be reached. In the TEST mode the start and trip signals of the relay module can be activated one by one. For further details see description "General characteristics of D type relay modules". |
| A | The address code of the protection relay module, required by the serial communication system. The address code is set at zero when no serial communication is to be used. The submenus of this register include the following settings or functions. - 1st submenu. Selection of data transfer rate for the communication system. Selectable values 4800 Bd or 9600 Bd. <br> - 2nd submenu. Bus communication monitor. If the relay is connected to bus communication unit, e.g. type SRIO 1000 M , and the communication system is working properly, the monitor shows the value zero. When the communication system is out of operation the values $0 \ldots 255$ scroll in the monitor. <br> 3rd submenu. Password for allowing remote changing of setting values. The password must always be given via the serial port. <br> - 4th submenu. Selection of main settings versus second settings. <br> - 5th submenu. Setting of the operate time of the circuit breaker failure protection unit. |
| - | Display dark. By pushing the STEP push-button the beginning of the display sequence is reached. |

Registers $1 . . .9$ are erased by pushing the RESET and PROGRAM push-buttons simultaneously. The contents of the registers are also erased if the auxiliary power supply of the module is interrupted. The address code of the relay module, the data transfer rate of the serial communica-
tion system, the password and the status of the main/second setting bank switch are not erased by a voltage failure. Instructions for setting the address and the data transfer rate are given in manual "General characteristics of D type relay modules".
 A

The procedures for entering a submenu or a setting mode and the method of performing the settings and the use of the TEST mode are
described in detail in the manual "General characteristics of D type relay modules". A short form guide to the operations is shown below.

| Desired step or setting operation | Push-button | Action |
| :--- | :--- | :--- |
| Forward step in main menu or submenu | STEP | Push for more than 0.5 s |
| Rapid scan forward in main menu | STEP | Keep pushing |
| Reverse step in main menu or submenu | STEP | Push less than about 0.5 s |
| Entering submenu from main menu | PROGRAM | Push for 1 s |
|  | (Active on release) |  |
| Entering or leaving setting mode | PROGRAM | Push for 5 s |
| Increasing value in setting mode | STEP | PROGRAM |
| Moving the cursor in setting mode | PROG about 1 s |  |
| Storing a value in setting mode | STEP\&PROGRAM | Push simultaneously |
| Erasing of memorized values and | STEP\&PROGRAM |  |
| resetting of latched output relays | PROGRAM | Note! Display must be off |
| Resetting of latched output relays | Note! All parameters which can be set in the setting mode are indicated with the symbol $\boldsymbol{f}$. |  |



Time/current characteristic (modified 2002-05)

The operation of the low-set overcurrent stage I> and the low-set earth-fault stage $\mathrm{I}_{0}>$ is based on definite time or inverse time characteristic, as selected by the user. The operation characteristic is selected with switches $1 . .3$ of switchgroup SGF1 for the overcurrent stage I> and with switches SGF1/6... 8 for the earth-fault stage $\mathrm{I}_{0}>$ (see chapter "Selector switches", page 7).

When IDMT characteristic has been selected, the operate time of the stage will be a function of the current; the higher the current, the shorter the operate time. The stage includes six time/ current curve sets - four according to the BS 142 and IEC 60255 standards and two special curve sets, named RI type and RXIDG type, according to ABB standards.

IDMT
characteristic

Four standard curves named extremely inverse, very inverse, normal inverse and long- time inverse are available. The relationship between current and time complies with the BS 142.1966 and IEC 60255-3 standards and can be expressed as follows:
$\mathrm{t}[\mathrm{s}]=\frac{\mathrm{kx} \beta}{\left(\frac{\mathrm{I}}{\mathrm{I}>}\right)^{\alpha}-1}$
where
$\mathrm{t}=$ operate time in seconds
$\mathrm{k}=$ time multiplier
I = measured current value
I> = set start current value

The relay includes four time/current curve sets according to BS 142.1966 and IEC 60255-3.

The slope of the time/current curve sets is determined by the constants $\alpha$ and $\beta$ as follows:

| Slope of the time/ <br> current curve set | $\alpha$ | $\beta$ |
| :--- | :--- | :---: |
| Normal inverse | 0.02 | 0.14 |
| Very inverse | 1.0 | 13.5 |
| Extremely inverse | 2.0 | 80.0 |
| Long-time inverse | 1.0 | 120.0 |

According to the standard BS 142.1966 the normal current range is defined as 2... 20 times the set start current. Additionally the relay must start at the latest when the current exceeds 1.3 times the set start current, when the time/ current characteristic is normal inverse, very inverse or extremely inverse. At long-time inverse characteristic, the normal range is $2 \ldots 7$ times the set start current and the relay must start when the current exceeds 1.1 times the setting.

The following requirements with regard to operate time tolerances are specified in the standard (E denotes accuracy in per cent, - = not specified):

| $\mathrm{I} / \mathrm{I}>$ | Normal inv. | Very inv. | Extremely inv. | Long-time inv. |
| :---: | :---: | :---: | :---: | :---: |
| 2 | 2.22 E | 2.34 E | 2.44 E | 2.34 E |
| 5 | 1.13 E | 1.26 E | 1.48 E | 1.26 E |
| 7 | - | - | - | 1.00 E |
| 10 | 1.01 E | 1.01 E | 1.02 E | - |
| 20 | 1.00 E | 1.00 E | 1.00 E | - |

In the defined normal current ranges, the in-verse-time stages of the overcurrent and earthfault unit SPCJ 4D29 comply with the tolerances of class 5 for all time/current curves.

The time/current curves specified in the BSstandards are illustrated in Fig. 3, 4, 5 and 6.

Note.
The actual operate time of the relay, presented in the graphs in Fig. 3...6, includes an additional filter and detection time plus the operate time of the trip output relay. When the operate time of the relay is calculated using the mathematical expression above, these additional times of about 30 ms in total have to be added to the time received.

RI-type
characteristic

The RI-type characteristic is a special characteristic used mainly in combination with existing mechanical relays. The characteristic is based on the following mathematical expression:
$\mathrm{t}[\mathrm{s}]=\frac{\mathrm{k}}{0.339-0.236 \times \frac{\mathrm{I}>}{\mathrm{I}}}$
where
$\mathrm{t}=$ operate time in seconds
$\mathrm{k}=$ time multiplier
I = measured phase current
I> = set start current

The graph of the characteristic is shown in Fig. 7.

RXIDG-type characteristic

The RXIDG-type characteristic is a special characteristic used mainly for earth-fault protection, where a high degree of selectivity is needed also for high-resistance faults. With this characteristic, the protection relay need not to be directional and the scheme can operate without a pilot communication.

The characteristic is based on the following mathematical expression:
$\mathrm{t}[\mathrm{s}]=5.8-1.35 \mathrm{x} \log _{\mathrm{e}}\left(\frac{\mathrm{I}}{\mathrm{kxI} \mathrm{l}}\right)$
where
$\mathrm{t}=$ operate time in seconds
$\mathrm{k}=$ time multiplier
I = measured phase current
I> = set start current

The graph of the characteristic is shown in Fig. 8.

Note!
If the set start current exceeds $2.5 \times \mathrm{I}_{\mathrm{n}}$, the maximum permitted continuous current carrying capacity of the energizing inputs ( $4 \times \mathrm{I}_{\mathrm{n}}$ ) must be observed.

At inverse time characteristic the effective setting range of the low-set overcurrent stage is $0.5 \ldots 2.5 \times \mathrm{I}_{\mathrm{n}}$, although start current settings within the range $2.5 \ldots 5.0 \mathrm{xI}_{\mathrm{n}}$ can be set on the relay. At inverse time characteristic any start
current setting above $2.5 \mathrm{x}_{\mathrm{n}}$ of the low-set stage will be regarded as being equal to $2.5 \mathrm{xI}_{\mathrm{n}}$.

The operation of the low-set stage based on inverse time characteristic will be blocked by starting of the high-set stage. Then the operate time of the overcurrent or earth-fault unit is determined by the set operate time of the highset stage at heavy fault currents.


Fig. 3. Extremely inverse-time characteristics of the overcurrent and earth-fault unit SPCJ 4D29.


Fig. 4. Very inverse-time characteristics of the overcurrent and earth-fault unit SPCJ 4D29.


Fig. 5. Normal inverse-time characteristics of the overcurrent and earth-fault unit SPCJ 4D29.


Fig. 6. Long-time inverse-time characteristics of the overcurrent and earth-fault unit SPCJ 4D29.


Fig. 7. RI-type inverse-time characteristics of the overcurrent and earth-fault unit SPCJ 4D29.


Fig. 8. RXIDG-type inverse-time characteristics of the overcurrent and earth-fault unit SPCJ 4D29.

Start current

- definite time characteristic
- inverse time characteristic

Start time, typ.
Operation characteristic

- definite time characteristic - operate time
- Inverse time characteristic acc. to BS 142 and IEC 60255-3
- special characteristic acc. to ABB standards
- time multiplier k

Reset time, typ.
Retardation time
Drop-off/pick-up ratio, typ.
Operate time accuracy at definite time operation characteristic
Operate time accuracy class E at inverse time characteristic
Operation accuracy

## High-set overcurrent stage l>>

Start current I>>
Start time, typ.
Operate time
Reset time, typ.
Retardation time
Drop-off/pick-up ratio, typ.
Operate time accuracy
Operation accuracy

## Low-set earth-fault stage $\mathrm{I}_{0}>$

Start current $\mathrm{I}_{0}>$
Start time, typ.
Operation characteristic

- definite time characteristic - operate time
- Inverse time characteristic acc. to BS 142 and IEC 60255-3
- special characteristic acc. to ABB standards
- time multiplier $\mathrm{k}_{0}$

Reset time, typ.
Retardation time
Drop-off/pick-up ratio, typ.
Operate time accuracy at definite time operation characteristic
Operate time accuracy class E at inverse time characteristic
Operation accuracy
$0.5 . .5 .0 \mathrm{x}_{\mathrm{n}}$ $0.5 \ldots 2.5 \times \mathrm{I}_{\mathrm{n}}$ 50 ms
$0.05 \ldots 300 \mathrm{~s}$
Extremely inverse
Very inverse
Normal inverse
Long-time inverse
RI-type inverse
RXIDG-type inverse
0.05...1.00

40 ms
$<30 \mathrm{~ms}$
0.96
$\pm 2 \%$ of set value or $\pm 25 \mathrm{~ms}$
5
$\pm 3 \%$ of set value
$0.5 \ldots 40.0 \times \mathrm{I}_{\mathrm{n}}$ or $\infty$, infinite
40 ms
$0.04 \ldots 300 \mathrm{~s}$
40 ms
$<30 \mathrm{~ms}$
0.98
$\pm 2 \%$ of set value or $\pm 25 \mathrm{~ms}$
$\pm 3 \%$ of set value
$0.1 \ldots 0.8 \mathrm{x}_{\mathrm{n}}$
60 ms
$0.05 \ldots 300 \mathrm{~s}$
Extremely inverse
Very inverse
Normal inverse
Long-time inverse
RI-type inverse
RXIDG-type inverse
0.05...1.00

40 ms
$<30 \mathrm{~ms}$
0.96
$\pm 2 \%$ of set value or $\pm 25 \mathrm{~ms}$

5
$\pm 3 \%$ of set value

Start current $\mathrm{I}_{0} \gg$
Start time, typ.
Operate time
Reset time, typ.
Drop-off/pick-up ratio, typ.
Operate time accuracy
Operation accuracy
0.1...10.0 $\mathrm{x}_{\mathrm{n}}$ or $\infty$, infinite

40 ms
$0.05 \ldots 300$ s
40 ms
0.98
$\pm 2 \%$ of set value or $\pm 25 \mathrm{~ms}$
$\pm 3 \%$ of set value

## Serial <br> communication parameters

Event codes

When the combined overcurrent and earthfault relay module SPCJ 4D29 is connected to a data communication unit. e.g. SRIO 1000M, over a fibre-optic SPA bus, the module will spontaneously generate event markings e.g. for a printer. The events are printed out in the format: time, text and event code. The text can be defined and written by the user into the communication unit.

The events coded E1...E16 can be included in or excluded from the event reporting by writing an event mask V155 for the overcurrent events and V156 for earth-fault events to the module over the SPA bus. The event masks are binary numbers coded to decimal numbers. The event codes E1...E8 are represented by the numbers 1, $2,4 \ldots 128$. An event mask is formed by multiplying the above numbers either by 0 , event not included in reporting, or 1 , event included in reporting and by adding the numbers received. Check for the procedure of a manual calculation of the checksum.

The event masks V155 and V156 may have a value within the range $0 \ldots 255$. The default value of the combined overcurrent and earthfault relay module SPCJ 4D29 is 85 both for overcurrent and earth-fault events, which means that all start and operate events are included in the reporting, but not the resetting. Check for
the procedure of a manual calculation of the checksum.

The output signals are monitored by codes E17...E26 and these events can be included in or excluded from the event reporting by writing an event mask V157 to the module. The event mask is a binary number coded to a decimal number. The event codes E17...E26 are represented by the numbers 1, 2, 4...512. An event mask is formed by multiplying the above numbers either by 0 , event not included in reporting or 1 , event included in reporting and by adding the numbers received. Check for the procedure of a manual calculation of the checksum.

The event mask V157 may have a value within the range $0 \ldots 1024$. The default value of the combined overcurrent and earth-fault relay module SPCJ 4D29 is 768 which means that only the operations are included in the reporting.

Codes E50...E54 and the events represented by these cannot be excluded from the reporting.

More information about the serial communication over the SPA bus can be found in the manual "SPA bus communication protocol", code No 34 SPACOM 2 EN1.

Event codes of the combined overcurrent and earth-fault relay module SPCJ 4D29:

| Code | Event | Weight factor | Default value <br> of the factor |
| :--- | :--- | :---: | :---: |
| E1 | Starting of stage I> | 1 | 1 |
| E2 | Resetting of starting of stage I> | 2 | 0 |
| E3 | Operation of stage I $>$ |  |  |
| E4 | Resetting of operation of stage I> | 4 | 1 |
| E5 | Starting of stage I>> | 8 | 0 |
| E6 | Resetting of starting of stage I>> | 16 | 1 |
| E7 | Operation of stage I>> |  |  |
| E8 | Resetting of operation of stage I>> | 62 | 0 |
|  | Default checksum for mask V155 | 128 | 1 |


| Code | Event | Weight factor | Default value of the factor |
| :---: | :---: | :---: | :---: |
| E9 | Starting of stage $\mathrm{I}_{0}>$ | 1 | 1 |
| E10 | Resetting of starting of stage $\mathrm{I}_{0}>$ | 2 | 0 |
| E11 | Operation of stage $\mathrm{I}_{0}>$ | 4 | 1 |
| E12 | Resetting of operation of stage $\mathrm{I}_{0}>$ | 8 | 0 |
| E13 | Starting of $\mathrm{I}_{0} \gg$ stage | 16 | 1 |
| E14 | Resetting of starting of stage $\mathrm{I}_{0} \gg$ | 32 | 0 |
| E15 | Operation of stage $\mathrm{I}_{0} \gg$ | 64 | 1 |
| E16 | Resetting of operation of stage $\mathrm{I}_{0} \gg$ | 128 | 0 |
| Default checksum for mask V156 |  |  | 85 |


| E17 | Output signal TS1 activated | 1 | 0 |
| :--- | :--- | ---: | :--- |
| E18 | Output signal TS1 reset | 2 | 0 |
| E19 | Output signal SS1 activated | 4 | 0 |
| E20 | Output signal SS1 reset | 8 | 0 |
| E21 | Output signal SS2 activated | 16 | 0 |
| E22 | Output signal SS2 reset | 32 | 0 |
| E23 | Output signal SS3 activated | 64 | 0 |
| E24 | Output signal SS3 reset | 128 | 0 |
| E25 | Output signal TS2 activated | 256 | 1 |
| E26 | Output signal TS2 reset | 512 | 1 |
|  |  |  |  |


| E50 | Restarting | $*$ | - |
| :--- | :--- | :---: | :---: |
| E51 | Overflow of event register |  |  |
| E52 | Temporary interruption in data communication | $*$ | - |
| E53 | No response from the module over the data <br> communication | $*$ | - |
| E54 | The module responds again over the data <br> communication | $*$ | - |

0 not included in the event reporting
1 included in the event reporting

* no code number
- cannot be programmed

Note!
The event codes E52-E54 are generated by the data communication unit (SACO 100M, SRIO 500M, SRIO 1000 M , etc.)

Data to be transferred via the fibreoptic serial bus

In addition to the spontaneous data transfer the SPA bus allows reading of all input values (Ivalues), setting values ( $S$-values), information recorded in the memory ( V -values), and some other data. Further, part of the data can be altered by commands given over the SPA bus.

All the data are available in channel 0 .
$\mathrm{R}=$ data to be read from the unit
W = data to be written to the unit
$(\mathrm{P})=$ writing enabled by password

| Data | Code | Data <br> direction | Values |
| :--- | :--- | :--- | :--- |

## INPUTS

Current on phase L1 I1
Current on phase L2
I2
Current on phase L3
I3
Neutral current
Blocking or control signal

## OUTPUTS

| Starting of stage I> | O1 | R | $\begin{aligned} & 0=\mathrm{I}>\text { stage not started } \\ & 1=\mathrm{I}>\text { stage started } \end{aligned}$ |
| :---: | :---: | :---: | :---: |
| Operation of stage I> | O 2 | R | $\begin{aligned} & 0=\mathrm{I}>\text { stage not tripped } \\ & 1=\mathrm{I}>\text { stage tripped } \end{aligned}$ |
| Starting of stage I>> | O3 | R | $\begin{aligned} & 0=\mathrm{I} \gg \text { stage not started } \\ & 1=\mathrm{I} \gg \text { stage started } \end{aligned}$ |
| Operation of stage I>> | O4 | R | $\begin{aligned} & 0=\mathrm{I} \gg \text { stage not tripped } \\ & 1=\mathrm{I} \gg \text { stage tripped } \end{aligned}$ |
| Starting of stage $\mathrm{I}_{0}>$ | O5 | R | $\begin{aligned} & 0=\mathrm{I}_{0}>\text { stage not started } \\ & 1=\mathrm{I}_{0}>\text { stage started } \end{aligned}$ |
| Operation of stage $\mathrm{I}_{0}>$ | O6 | R | $\begin{aligned} & 0=I_{0}>\text { stage not tripped } \\ & 1=I_{0}>\text { stage tripped } \end{aligned}$ |
| Starting of stage $\mathrm{I}_{0} \gg$ | O7 | R | $\begin{aligned} & 0=\mathrm{I}_{0 \gg} \text { stage not started } \\ & 1=\mathrm{I}_{0 \gg} \text { stage started } \end{aligned}$ |
| Operation of stage $\mathrm{I}_{0} \gg$ | O8 | R | $\begin{aligned} & 0=\mathrm{I}_{0} \gg \text { stage not tripped } \\ & 1=\mathrm{I}_{0} \gg \text { stage tripped } \end{aligned}$ |
| Signal START1 TS1 | O9 | R, W (P) | $0=$ signal not active <br> $1=$ signal active |
| Signal START2 SS1 | O10 | R, W (P) | $0=$ signal not active <br> $1=$ signal active |
| Signal ALARM1 SS2 | O11 | R, W (P) | $0=$ signal not active <br> $1=$ signal active |
| Signal ALARM2 SS3 | O12 | R, W (P) | $0=$ signal not active <br> $1=$ signal active |
| Signal TRIP TS2 | O13 | R, W (P) | $0=$ signal not active <br> $1=$ signal active |
| Operate output relays | O41 | R, W (P) | $\begin{aligned} & 0=\text { not operated } \\ & 1=\text { operated } \end{aligned}$ |


| Data | Code | Data direction | Values |
| :---: | :---: | :---: | :---: |
| Memorized I> start signal | O21 | R | $\begin{aligned} & 0=\text { signal not active } \\ & 1=\text { signal active } \end{aligned}$ |
| Memorized $\mathrm{I}>$ operate signal | O22 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized I>> start signal | O23 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized I>> operate signal | O24 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized $\mathrm{I}_{0}>$ start signal | O25 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized $\mathrm{I}_{0}>$ operate signal | O26 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized $\mathrm{I}_{0} \gg$ start signal | O27 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized $\mathrm{I}_{0} \gg$ operate signal | O28 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized output signal TS1 | O29 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized output signal SS1 | O30 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized output signal SS2 | O31 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized output signal SS3 | O32 | R | $0=$ signal not active <br> $1=$ signal active |
| Memorized output signal TS2 | O33 | R | $0=$ signal not active <br> $1=$ signal active |

## PRESENT SETTING VALUES

Present start value for stage I>
Present operate time or time S2
multiplier for stage I>
Present start value for stage I>>
S3
Present operate time for stage I>> S4
Present start value for stage $\mathrm{I}_{0}>$ S5
Present operate time or time S6
multiplier for stage $\mathrm{I}_{0}>$
Present start value for stage $\mathrm{I}_{0} \gg \quad$ S7
Present operate time for stage $\mathrm{I}_{0} \gg \quad \mathrm{~S} 8$
Present checksum of S9
switchgroup SGF1
Present checksum of
switchgroup SGF2
Present checksum of S11
switchgroup SGB
Present checksum of
switchgroup SGR1
Present checksum of
switchgroup SGR2
Present checksum of
switchgroup SGR3

| Data | Code | Data <br> direction | Values |
| :--- | :--- | :--- | :--- |

## MAIN SETTING VALUES

Start current of stage I>, S21
main setting
Operate time or time multiplier
of stage I>, main setting
Start current of stage I>>,
main setting
Operate time of stage I>>,
main setting
Start current of stage $\mathrm{I}_{0}>, \quad$ S25
main setting
Operate time or time multiplier of stage $\mathrm{I}_{0}>$, main setting
Start current of stage $\mathrm{I}_{0} \gg$,
main setting
Operate time of stage $I_{0} \gg$,
main setting
Checksum of switchgroup SGF1, main setting
Checksum of switchgroup SGF2,
main setting
Checksum of switchgroup SGB,
main setting
Checksum of switchgroup SGR1, main setting
Checksum of switchgroup SGR2,
main setting
Checksum of switchgroup SGR3, main setting

## SECOND SETTING VALUES

| Start current of stage I>, second setting | S41 |
| :---: | :---: |
| Operate time or time multiplier of stage $I>$, second setting | S42 |
| Start current of stage I>>, second setting | S43 |
| Operate time of stage I>>, second setting | S44 |
| Start current of stage $\mathrm{I}_{0}>$, second setting | S45 |
| Operate time or time multiplier of stage $\mathrm{I}_{0}>$, second setting | S46 |
| Start current of stage $\mathrm{I}_{0} \gg$, second setting | S47 |
| Operate time of stage $\mathrm{I}_{0} \gg$, second setting | S48 |


| R, W (P) | $0.5 \ldots 5.0 \times \mathrm{I}_{n}$ |
| :---: | :---: |
| R, W (P) | 0.05... 300 s |
|  | 0.05...1.0 |
| R, W (P) | $0.5 \ldots .40 .0 \times \mathrm{I}_{\mathrm{n}}$ |
| R, W (P) | 0.04... 300 s |
| R, W (P) | $0.1 \ldots 0.8 \times \mathrm{I}_{\mathrm{n}}$ |
| R, W (P) | 0.05... 300 s |
|  | 0.05...1.0 |
| R, W (P) | $0.1 \ldots 10.0 \times \mathrm{I}_{\mathrm{n}}$ |
| R, W (P) | 0.05... 300 s |
| R, W (P) | 0... 255 |
| R, W (P) | 0... 255 |
| R, W (P) | 0... 255 |
| R, W (P) | 0... 255 |
| R, W (P) | 0... 255 |
| R, W (P) | 0... 255 |


| R, W (P) | $0.5 \ldots 5.0 \times I_{n}$ |
| :--- | :--- |
| R, W (P) | $0.05 \ldots 300 \mathrm{~s}$ |
| R, W (P) | $0.05 \ldots .5 . .40 .0 \times I_{n}$ |
|  |  |
| R, W (P) | $0.04 \ldots 300 \mathrm{~s}$ |
| R, W (P) | $0.1 \ldots 0.8 \times \mathrm{I}_{\mathrm{n}}$ |
|  |  |
| R, W (P) | $0.05 \ldots 300 \mathrm{~s}$ |
| R, W (P) | $0.05 \ldots 1.0$ |
|  | $0.10 .0 \times I_{n}$ |
| R, W (P) | $0.05 \ldots 300 \mathrm{~s}$ |


| Data | Code | Data direction | Values |
| :---: | :---: | :---: | :---: |
| Checksum of switchgroup SGF1, second setting | S49 | R, W (P) | 0... 255 |
| Checksum of switchgroup SGF2, second setting | S50 | R, W (P) | 0... 255 |
| Checksum of switchgroup SGB, second setting | S51 | R, W (P) | 0... 255 |
| Checksum of switchgroup SGR1, second setting | S52 | R, W (P) | 0... 255 |
| Checksum of switchgroup SGR2, second setting | S53 | R, W (P) | 0... 255 |
| Checksum of switchgroup SGR3, second setting | S54 | R, W (P) | 0... 255 |
| Operate time for the circuit breaker failure protection | S61 | R, W (P) | 0.1..1.0 s |

## RECORDED AND MEMORIZED PARAMETERS

| Current on phase L1 at starting or operation | V11...V51 | R | $0 . . .63 \times \mathrm{I}_{\mathrm{n}}$ |
| :---: | :---: | :---: | :---: |
| Current on phase L2 at starting or operation | V12...V52 | R | $0 . . .63 \times \mathrm{I}_{\mathrm{n}}$ |
| Current on phase L3 at starting or operation | V13...V53 | R | $0 . . .63 \times \mathrm{I}_{\mathrm{n}}$ |
| Neutral current $\mathrm{I}_{0}$ at starting or operation | V14...V54 | R | $0 . . .21 \times \mathrm{I}_{\mathrm{n}}$ |
| Duration of the latest start situation of stage I> | V15...V55 | R | 0...100\% |
| Duration of the latest start situation of stage I>> | V16...V56 | R | 0...100\% |
| Duration of the latest start situation of stage $I_{0}>$ | V17...V57 | R | 0...100\% |
| Duration of the latest start situation of stage $\mathrm{I}_{0} \gg$ | V18...V58 | R | 0...100\% |
| Maximum demand current for 15 min . | V1 | R | $0 . .2 .5 \mathrm{x} \mathrm{I}_{\mathrm{n}}$ |
| Number of starts of stage I> | V2 | R | 0... 255 |
| Number of starts of stage I>> | V3 | R | 0... 255 |
| Number of starts of stage $\mathrm{I}_{0}>$ | V4 | R | 0... 255 |
| Number of starts of stage $\mathrm{I}_{0} \gg$ | V5 | R | 0... 255 |
| Phase conditions during trip | V6 | R | $\begin{array}{rlrl} 1 & =I_{\mathrm{L} 3>}> & 2 & =\mathrm{I}_{\mathrm{L} 2}> \\ 4 & =\mathrm{I}_{\mathrm{L} 1}>, & 8 & =\mathrm{I}_{0}> \\ 16 & =\mathrm{I}_{\mathrm{L} 3 \gg}> & 32 & =\mathrm{I}_{\mathrm{L} 2 \gg}> \\ 64 & =\mathrm{I}_{\mathrm{L} 1 \gg,}>128 & =\mathrm{I}_{0} \gg \end{array}$ |
| Operation indicator | V7 | R | 0...9 |
| Highest maximum demand current 15 minute value | V8 | R | $0 . .2 .55 \mathrm{x} \mathrm{I}_{\mathrm{n}}$ |

## CONTROL PARAMETERS

Resetting of output relays
at latched output
Resetting of output relays
and recorded data

| V101 W | 1 $=$output relays and all <br> information from the <br> display are reset <br> V102 W$\quad$output relays and <br> registers are reset |
| :---: | :---: | :---: |


| Data | Code | Data <br> direction | Values |
| :--- | :--- | :--- | :--- |
| Remote control of settings | V150 | R, W | 0 = main settings activated <br> $1=$ second settings activated, <br> see chapter "Description <br> of function" |
|  |  |  | V155 |

The event register can be read by L-command only once. Should a fault occur e.g. in the data transfer, the contents of the event register may be re-read using the B -command. When required, the B -command can be repeated. Generally, the control data communicator SACO 100 M reads the event data and forwards them to the output device continuously. Under normal conditions the event register of the module is empty. The data communicator also resets abnormal status data, so this data is normally a zero.

The setting values $S 1 \ldots S 14$ are the setting values used by the protection functions. All the settings can be read or written. A condition for writing is that remote set password has been opened.

When changing settings, the relay unit will check that the variable values are within the ranges specified in the technical data of the module. If a value beyond the limits is given to the unit, either manually or by remote setting, the unit will not perform the store operation but will keep the previous setting.

Shortly after the internal self-supervision system has detected a permanent relay fault, the red IRF indicator is lit and the output relay of the selfsupervision system operates. Further, in most fault situations, an auto-diagnostic fault code is shown on the display. This fault code consists of a red figure 1 and a green code number which
indicates the fault type. When a fault code appears on the display, the code number should be recorded and given to the authorized repair shop when overhaul is ordered. In the table below some fault codes that might appear on the display of the SPCJ 4D29 module are listed:

| Fault code | Type of error in module |
| :---: | :--- |
| 4 | Faulty trip relay path or missing output relay card |
| 30 | Faulty program memory (ROM) |
| 50 | Faulty work memory (RAM) |
| 51 | Parameter memory (EEPROM) block 1 faulty |
| 52 | Parameter memory (EEPROM) block 2 faulty |
| 53 | Parameter memory (EEPROM) block 1 and block 2 faulty |
| 54 | Parameter memory (EEPROM) block 1 and block 2 faulty with different |
| 56 | checksums |
|  | Parameter memory (EEPROM) key faulty. Format by writing a "2" to |
| 195 | variable V167 |
| 131 | Too low value in reference channel with multiplier 1 |
| 67 | Too low value in reference channel with multiplier 5 |
| 203 | Too low value in reference channel with multiplier 25 |
| 139 | Too high value in reference channel with multiplier 1 |
| 75 | Too high value in reference channel with multiplier 5 |
| 252 | Too high value in reference channel with multiplier 25 |
| 253 | Faulty filter on I I channel |
| No interruptions from the A/D-converter |  |

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